An Introduction to Optimization Using Genetic/Evolutionary Algorithms

Part I

Single and Multi-Objective Problems

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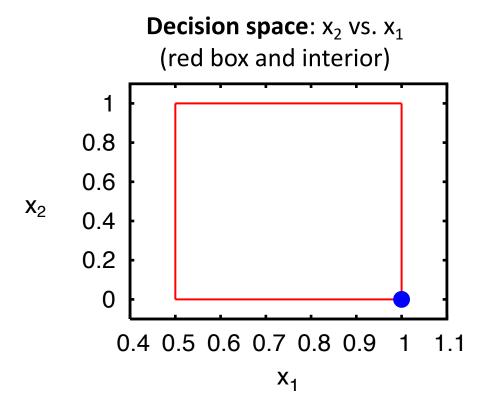
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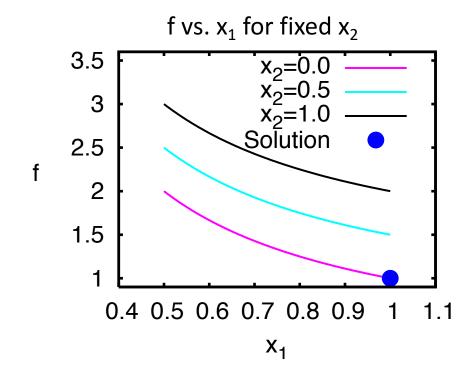


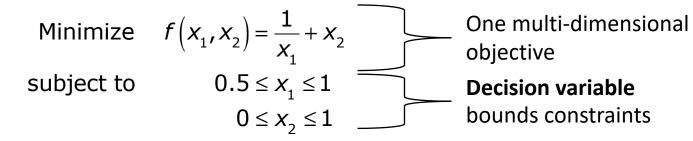




Single-Objective Example

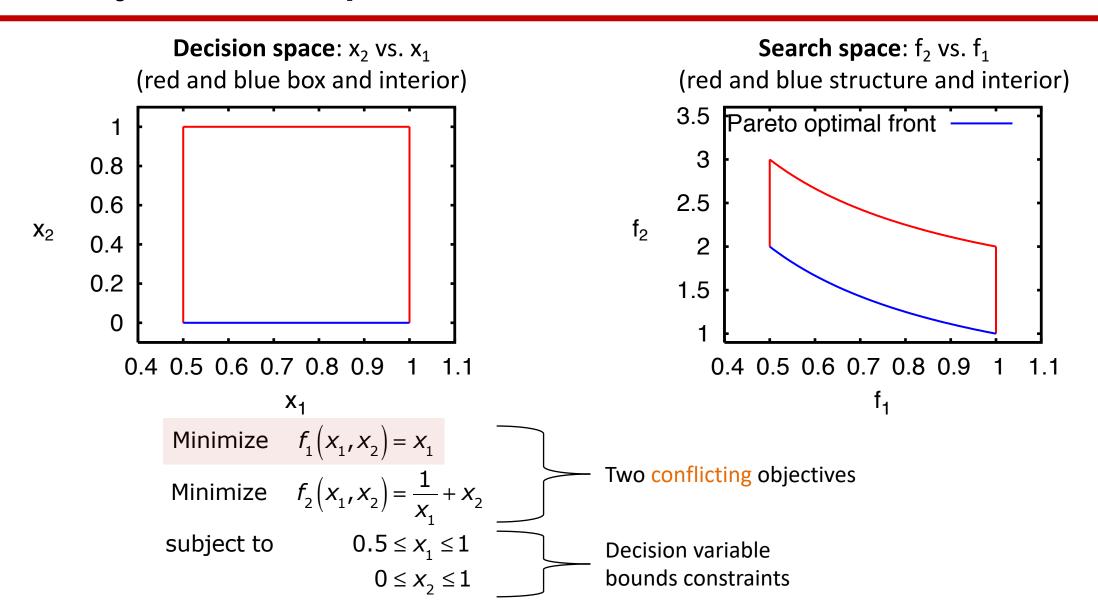






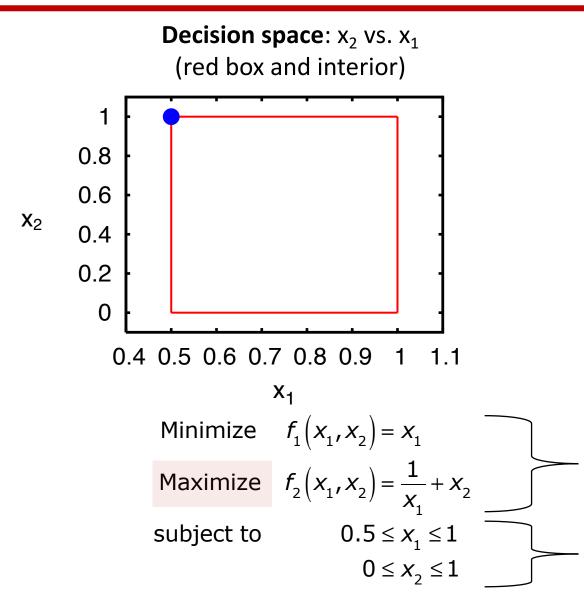


Multi-Objective Example 1

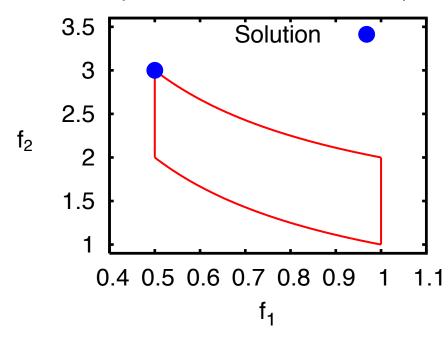




Multi-Objective Example 2



Search space: f₂ vs. f₁ (red structure and interior)



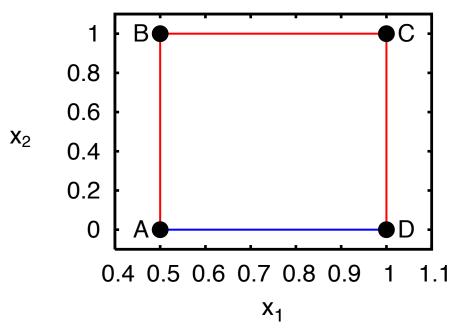
Objectives do not conflict

Decision variable bounds constraints



Multi-Objective Example 1





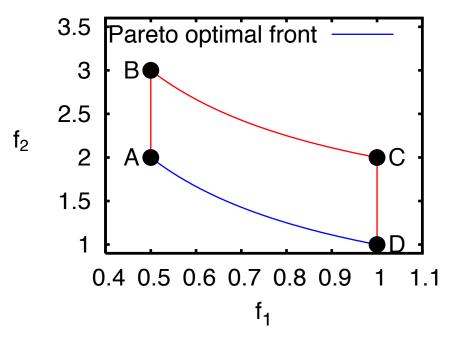
Dominance

- An individual dominates another if it is better in at least one objective and no worse in the remainder
- "Better" = "<" and "no worse" = "≤" for minimization</p>

Pareto optimality

- Trade-offs between objectives
- Non-dominated individuals that dominate at least one other individual

Search space: f₂ vs. f₁



- For A, B, C, and D in f₂ vs. f₁
 - A dominates B and C but not D
 - D dominates C but not A and B
 - B and C do not dominate
 - A and D are non-dominated
 - Blue curve is Pareto optimal front
 - A and D are on the Pareto optimal front

Terminology for Multi-Objective Optimizations and Genetic/Evolutionary Algorithms

- Decision variable = independent variable
- Decision space is the domain of the optimization problem and is the volume of all possible combinations of decision variable values
- Search space is the range of the optimization problem and is the volume of all possible combinations of objective values
- Conflicting objectives are objectives for which given decision variable values have the opposite effects (work against each other) and lead to sets of solutions
- Dominance: concept from natural selection used to categorize solution "performance" with respect to other solutions and the optimization goals
- Pareto Optimality: concept from economics indicating that solutions are equally good and have trade-offs

