



Mentor: Max Bruker

JLab SRGS

June - July 2024

2024



Presentation by
Zane Geadah



JLab Portfolio



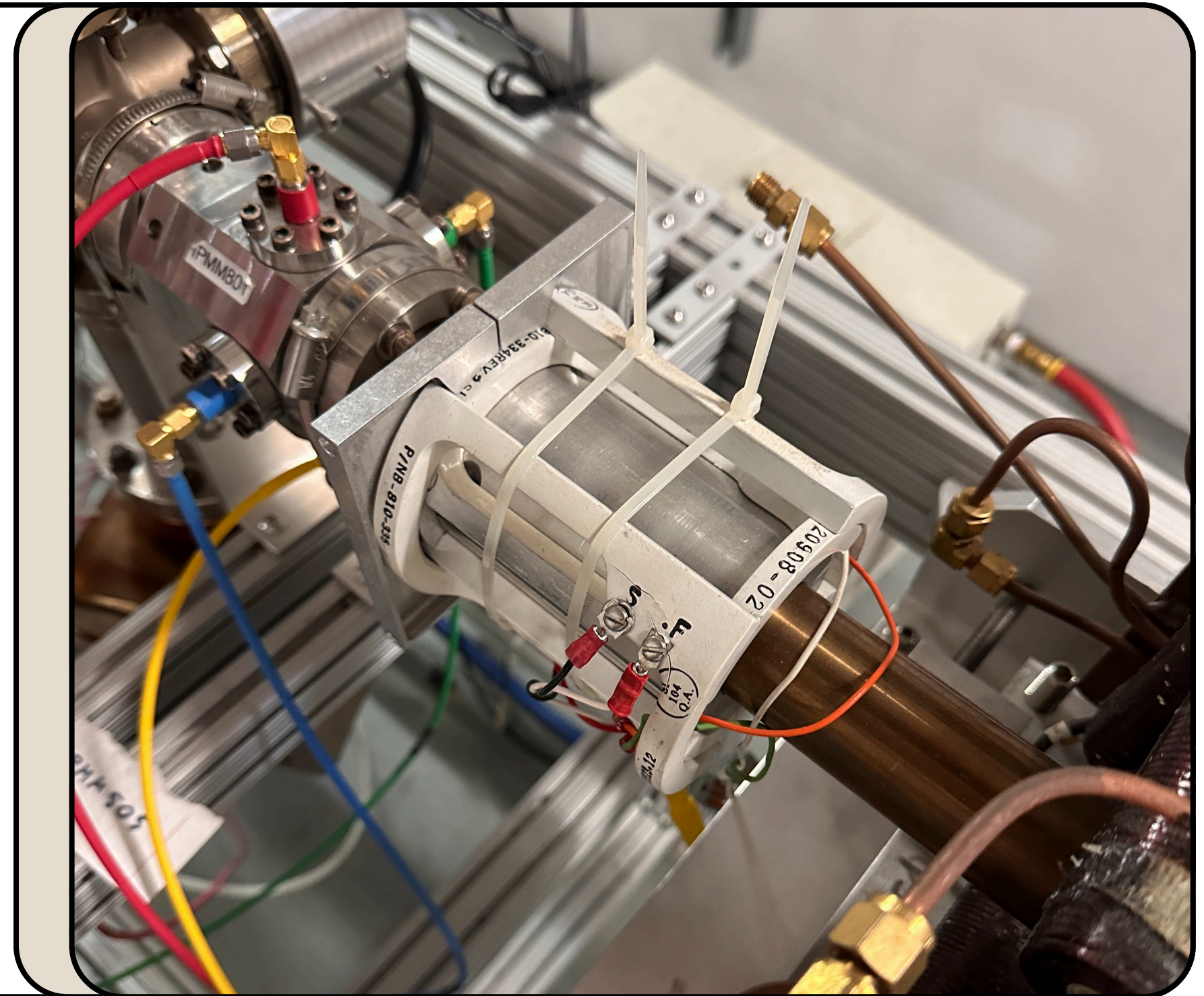
3D Printing & Testing Corrector Magnet Fixtures for the UITF



Introduction *

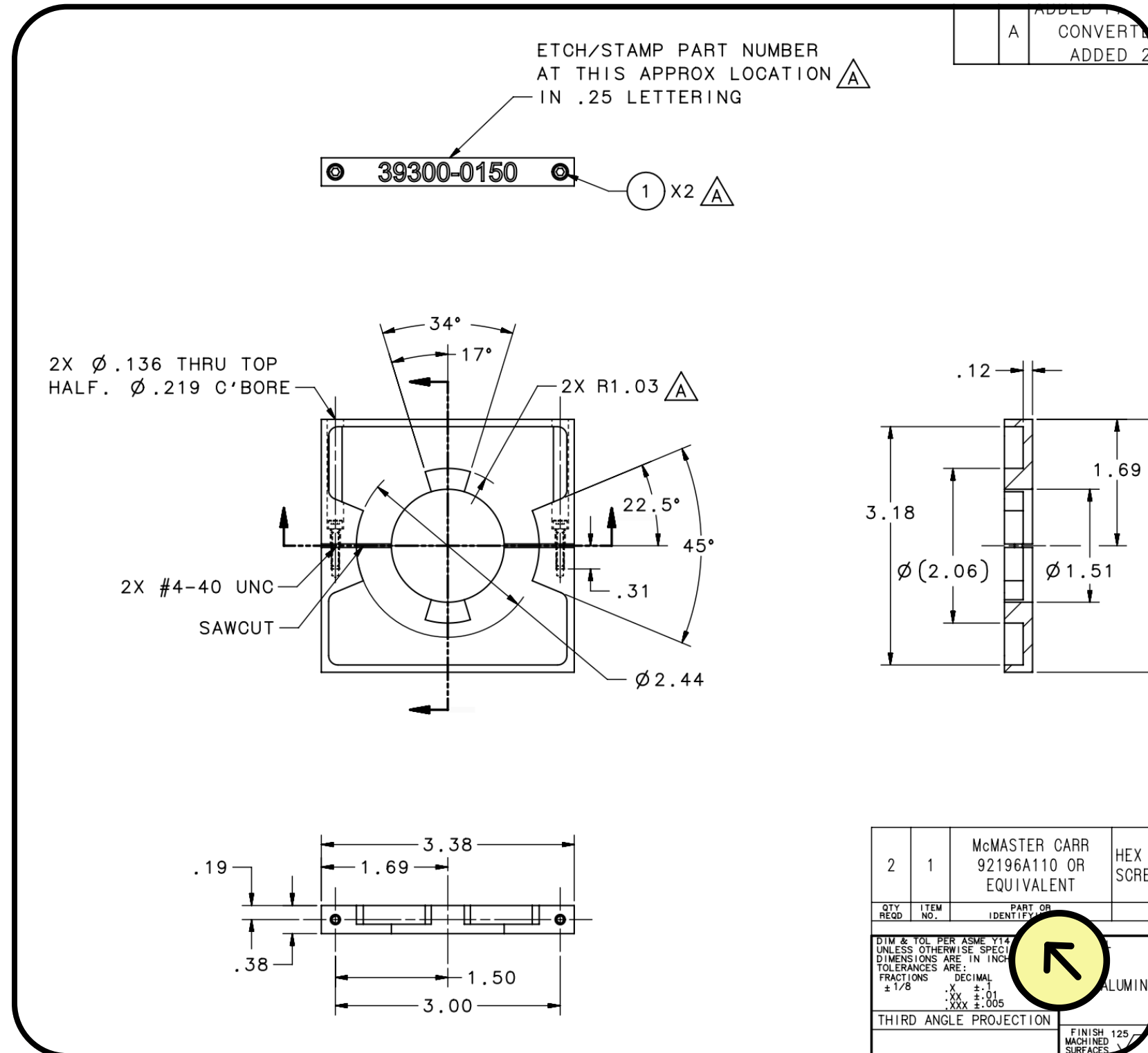
UITF

- **My Project**
- **Why?**
 - **Cost, Time, Accuracy**
- **Magnetic Declination**
 - **JLab -> 37.1° N, 76.5° W**
10.76° W, 49,454.8 nT
(Nano-Tesla)

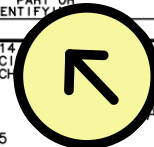


Design Process Pt. 1 *

Blueprint

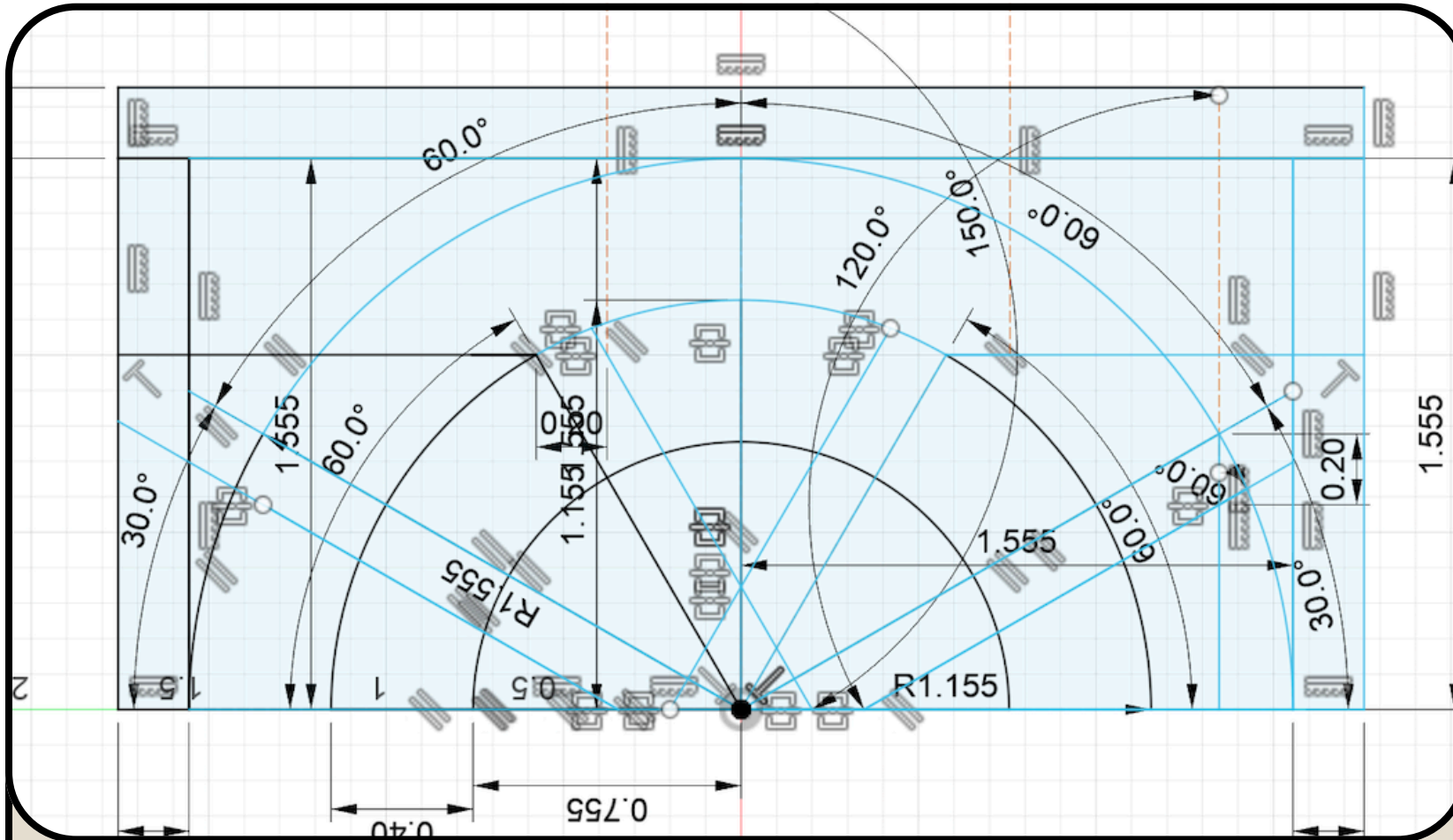


- Old Design
 - 0150 vs. 0151
- Components
- Failures



Design Process Pt. 2 *

Fusion 360



**Initial over constrained model of the
0150 fixture in Fusion 360**



- **Modeling**
 - **Fusion 360**
- **Initial Set-Backs**
 - **Over-constrained**



Design Process Pt. 3 *

CMM



	NOMINAL	+TOL	-TOL
	-2.171	0.100	0.100
	5.116	0.100	0.100
	28.550	0.100	0.100
IM	LOC2 - B-OUTER-CIR		
	NOMINAL	+TOL	-TOL
	-2.295	0.100	0.100
	5.453	0.100	0.100
	37.838	0.050	0.050
EG	ANGL1 - LIN1 TO LIN2		
	NOMINAL	+TOL	-TOL
	59.707	0.100	0.100
IM	LOC3 - A-INNER		
	NOMINAL	+TOL	-TOL
	-3.495	0.100	0.100
	4.304	0.100	0.100
	28.610	0.050	0.050
IM	LOC4 - A-OUTER		
	NOMINAL	+TOL	-TOL
	-3.568	0.100	0.100
	4.502	0.100	0.100
	37.846	0.050	0.050
EG	ANGL2 - LIN3 TO LIN4		
	NOMINAL	+TOL	-TOL
	59.645	0.100	0.100

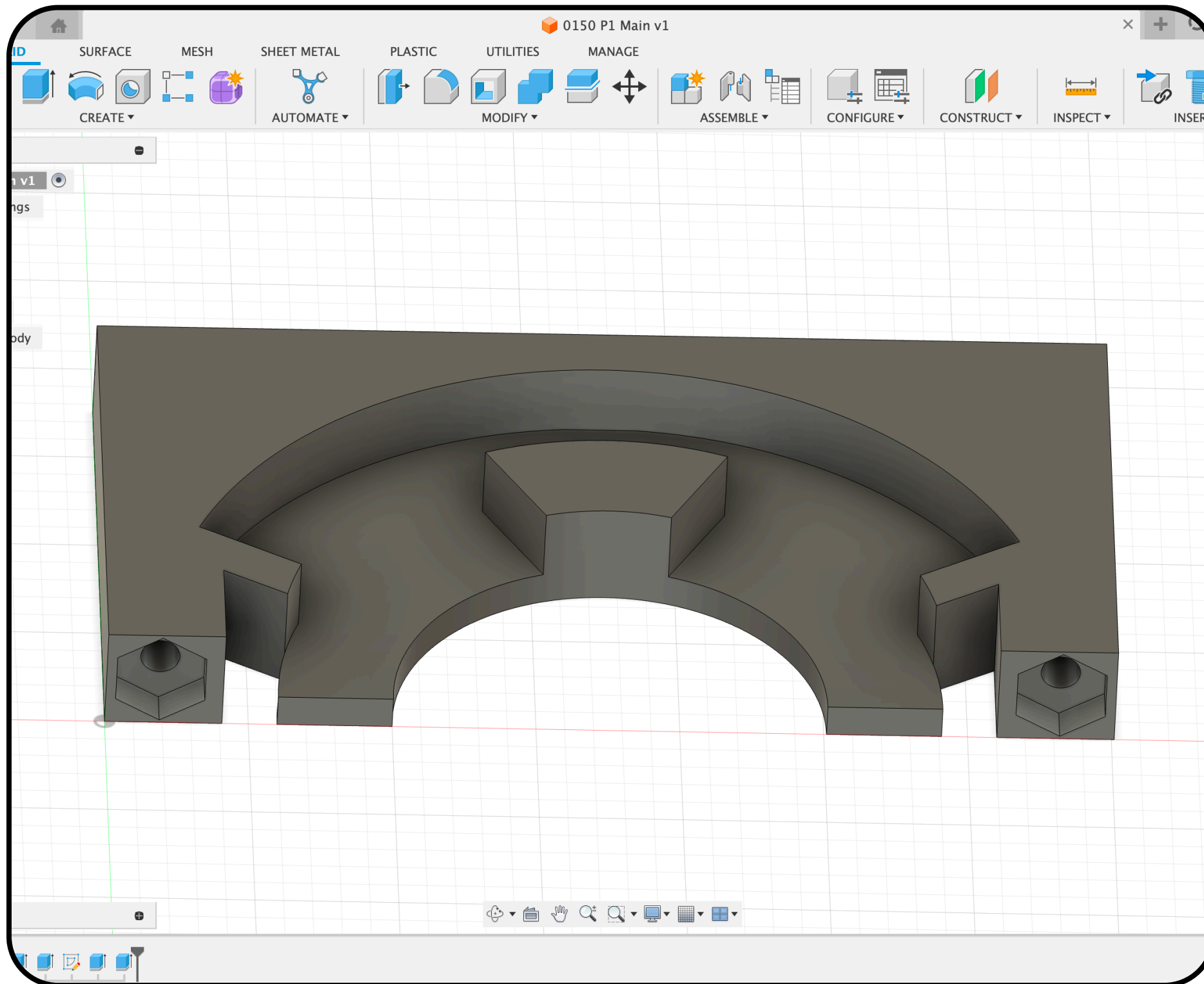


- **CMM Process**
- **Output Data**
 - **Old Part's Deviation**
- **Utilization**



Design Process Pt. 4 *

Version-2

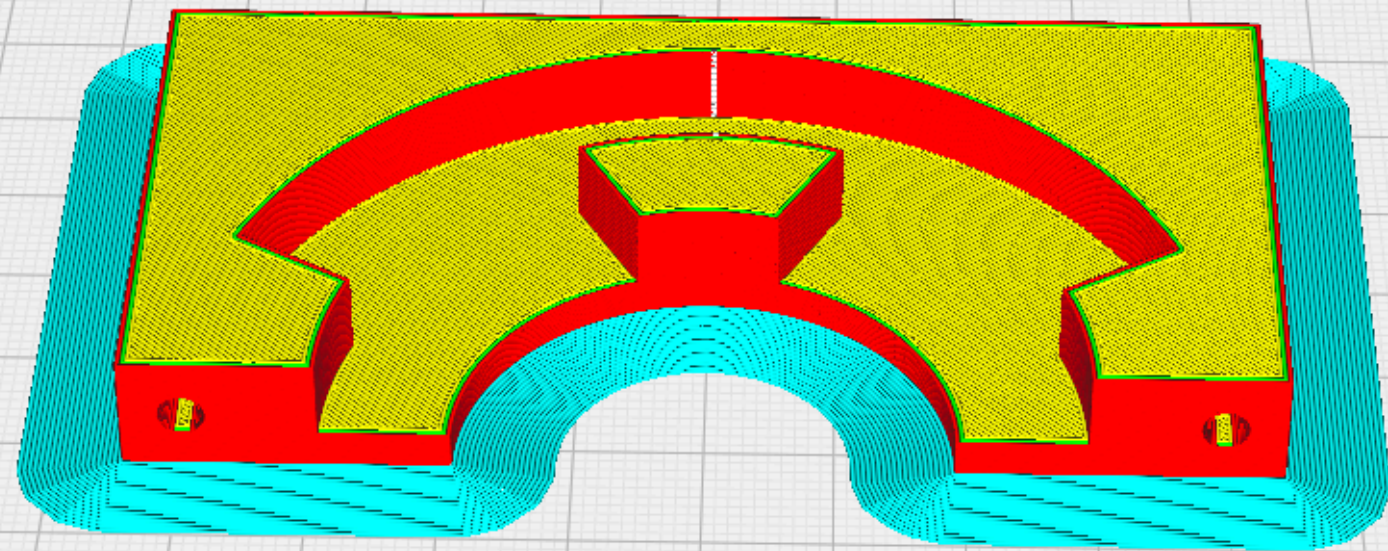


- **V1 - V3**
- **Hardware**
- **Process**



3D-Printing Pt. 1 *

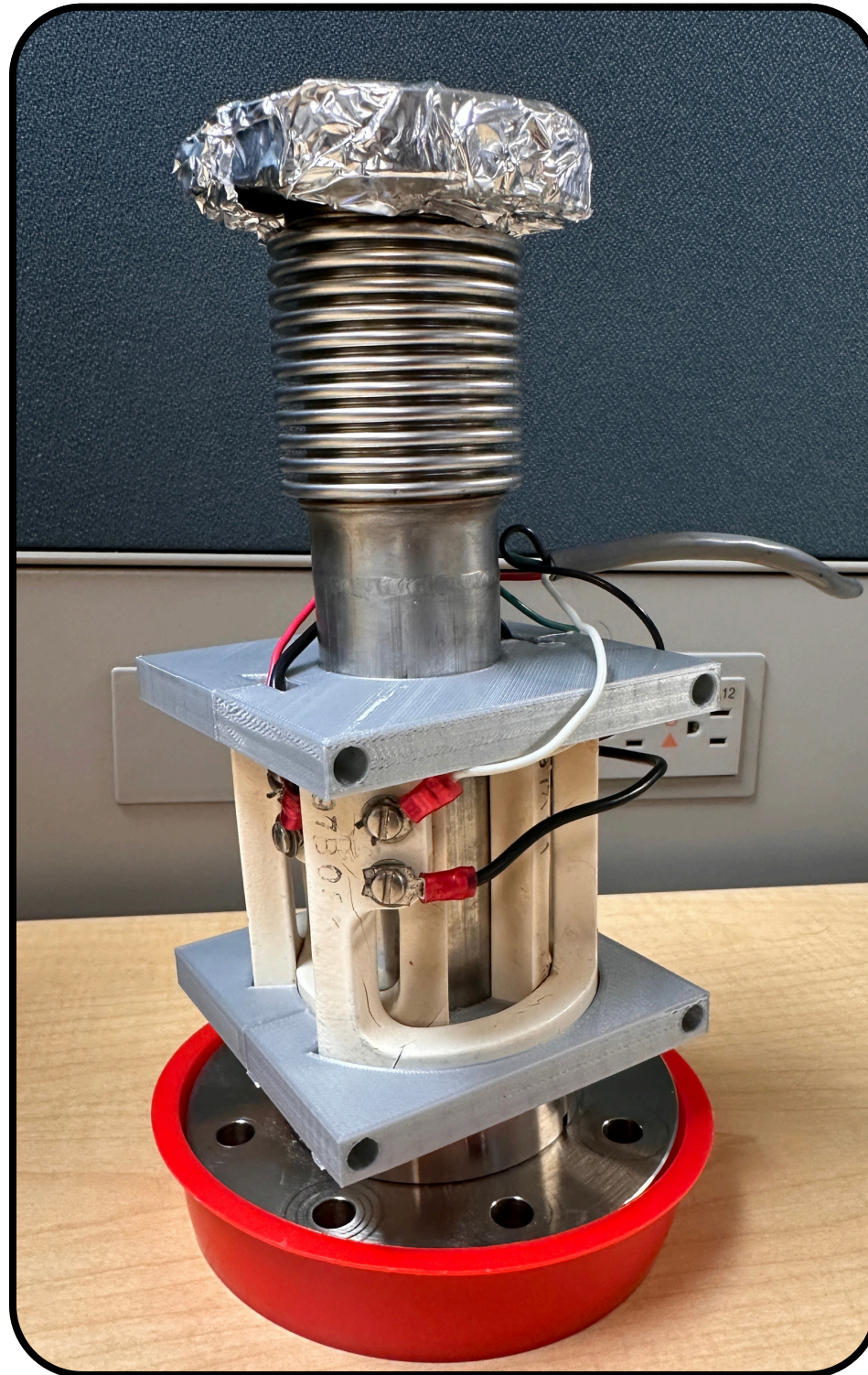
Cura



- **Printer** ✨
- **Platform**
- **Settings**
 - **Temp, Precision, Speed, Infill**

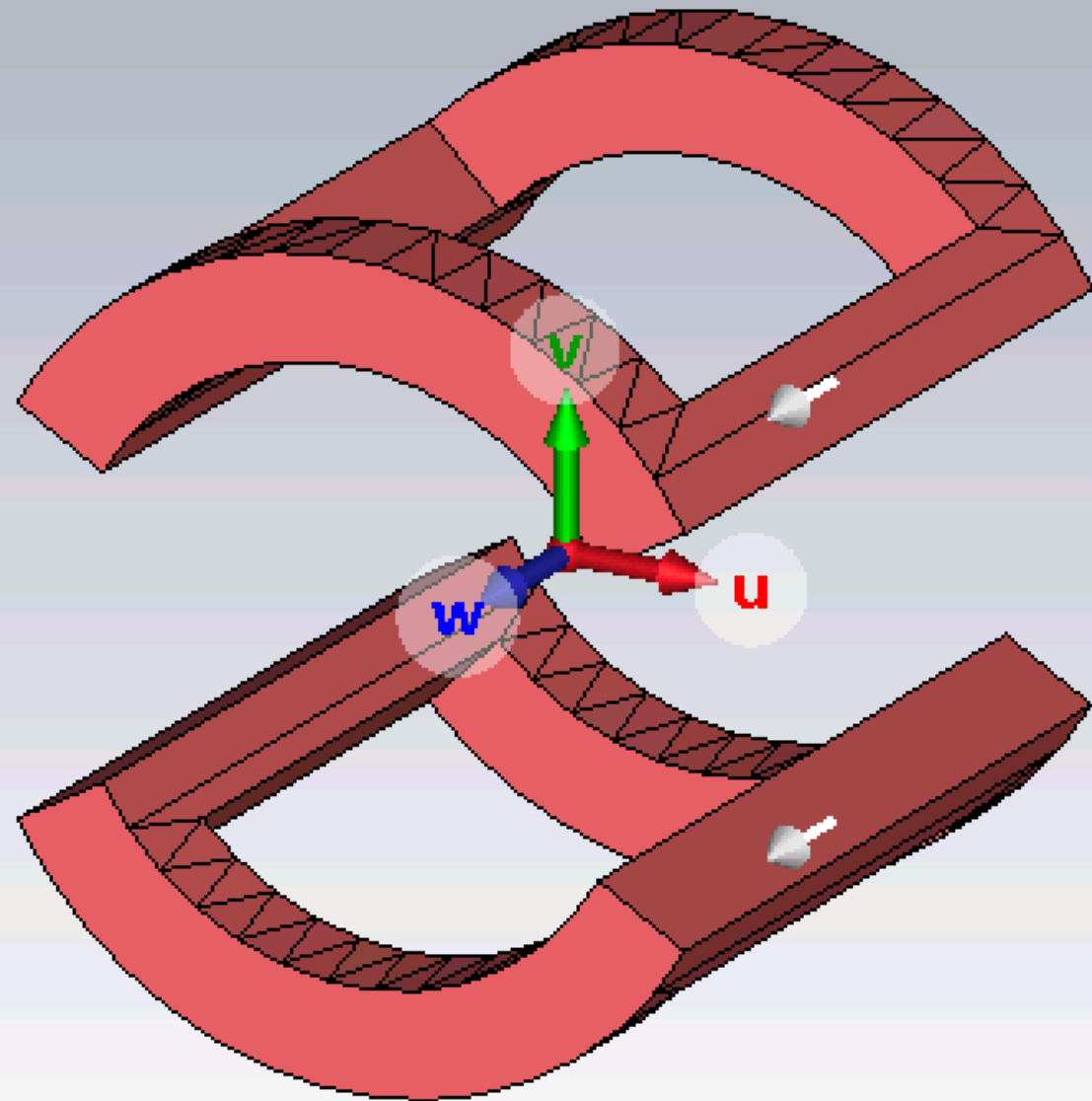
3D-Printing Pt. 2 *

Initial Test




- **Initial Test**
- **Successes**
- **Failures**

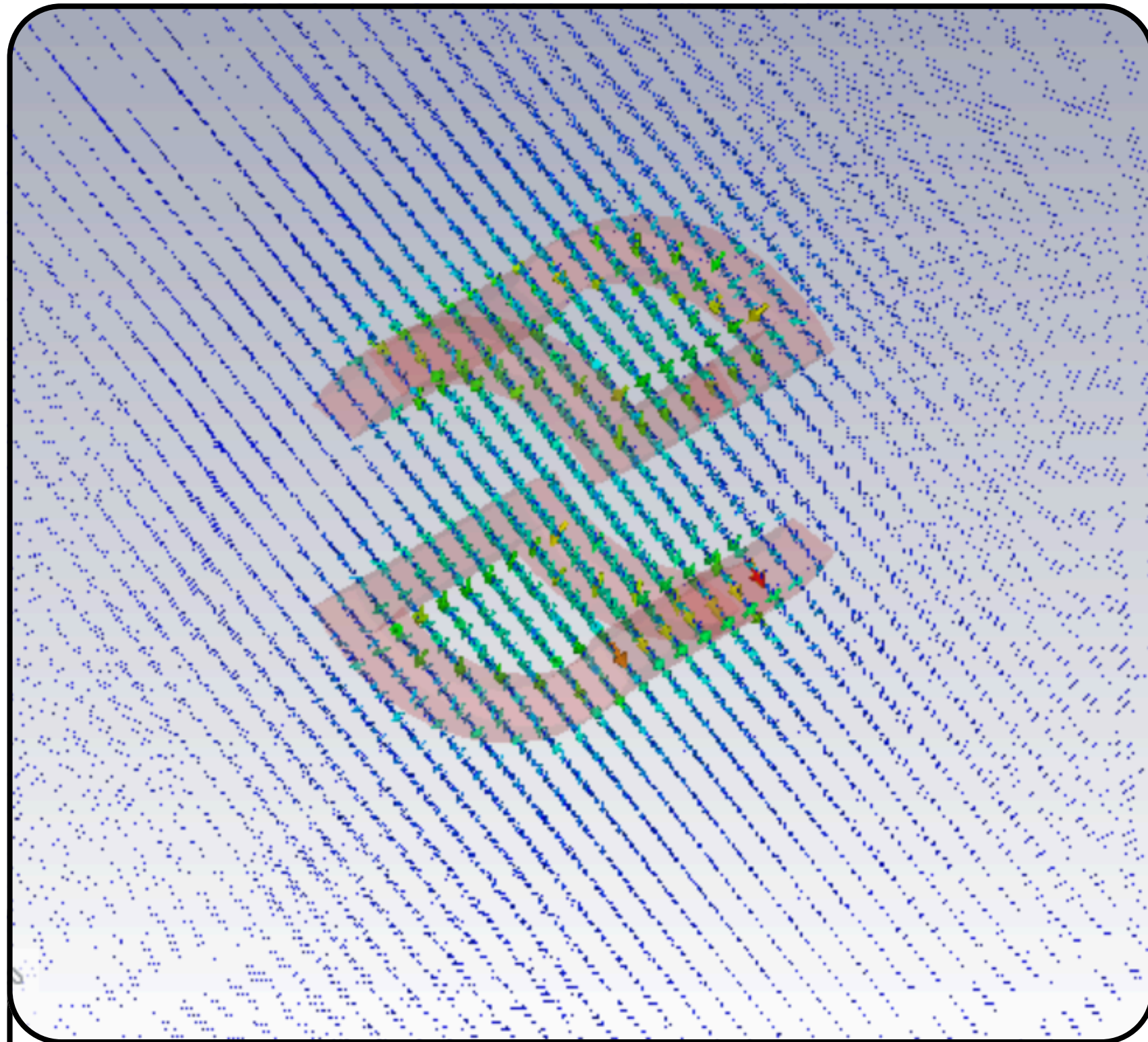
CST Setup




0150 corrector magnet model with corresponding coils and current

- **Model** 
- **Coil Conversion**
 - **WCS Plane**
- **Parameters**
 - **1 amp, 1 turn, direction**

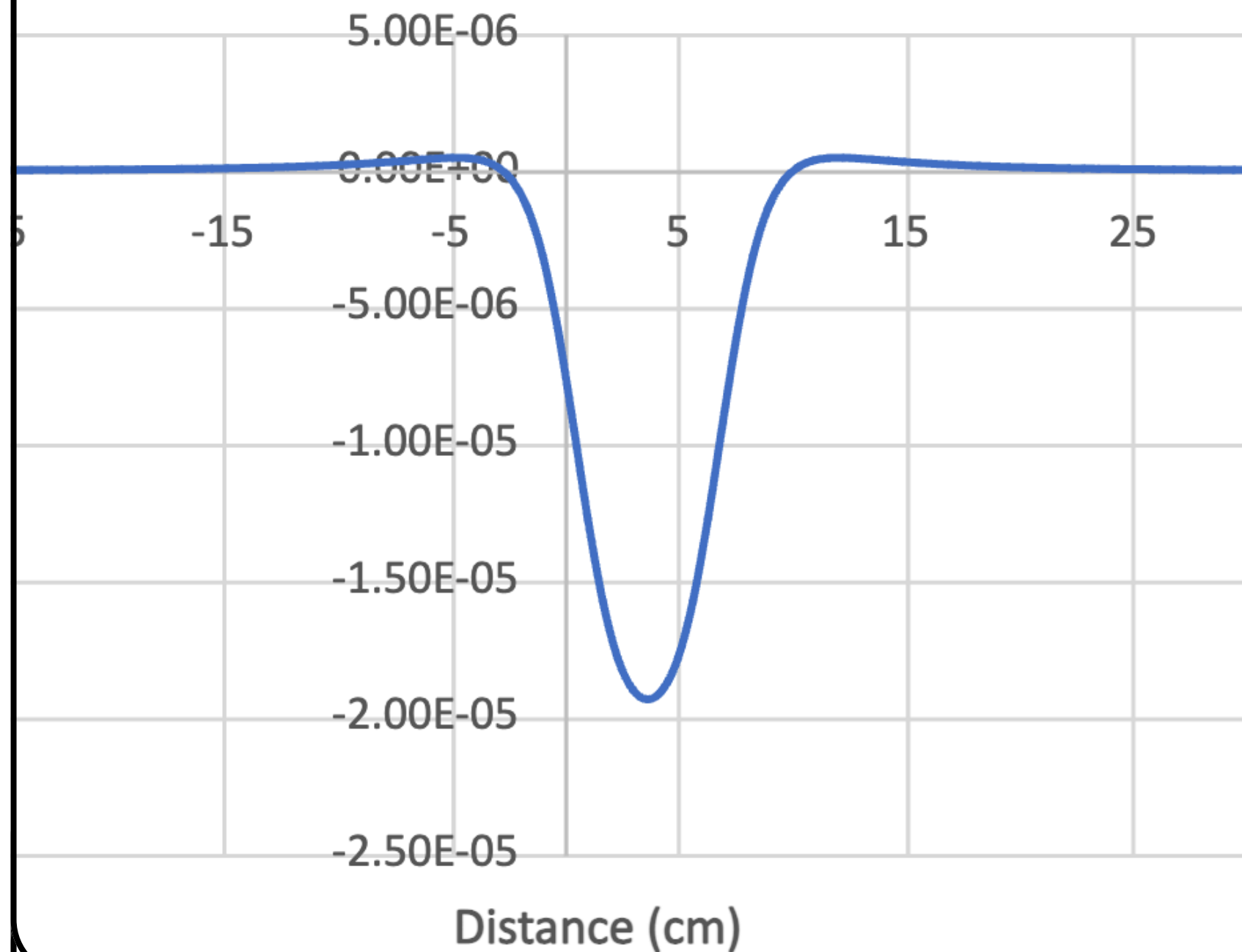
CST Testing



Calculated magnetic mesh field with
over 7,000,000 tetrahedrons

- **Setup** 
- **Box + Mesh Density**
- **Calculations**
- **Outcome**

Corrector Magnet's B - Field



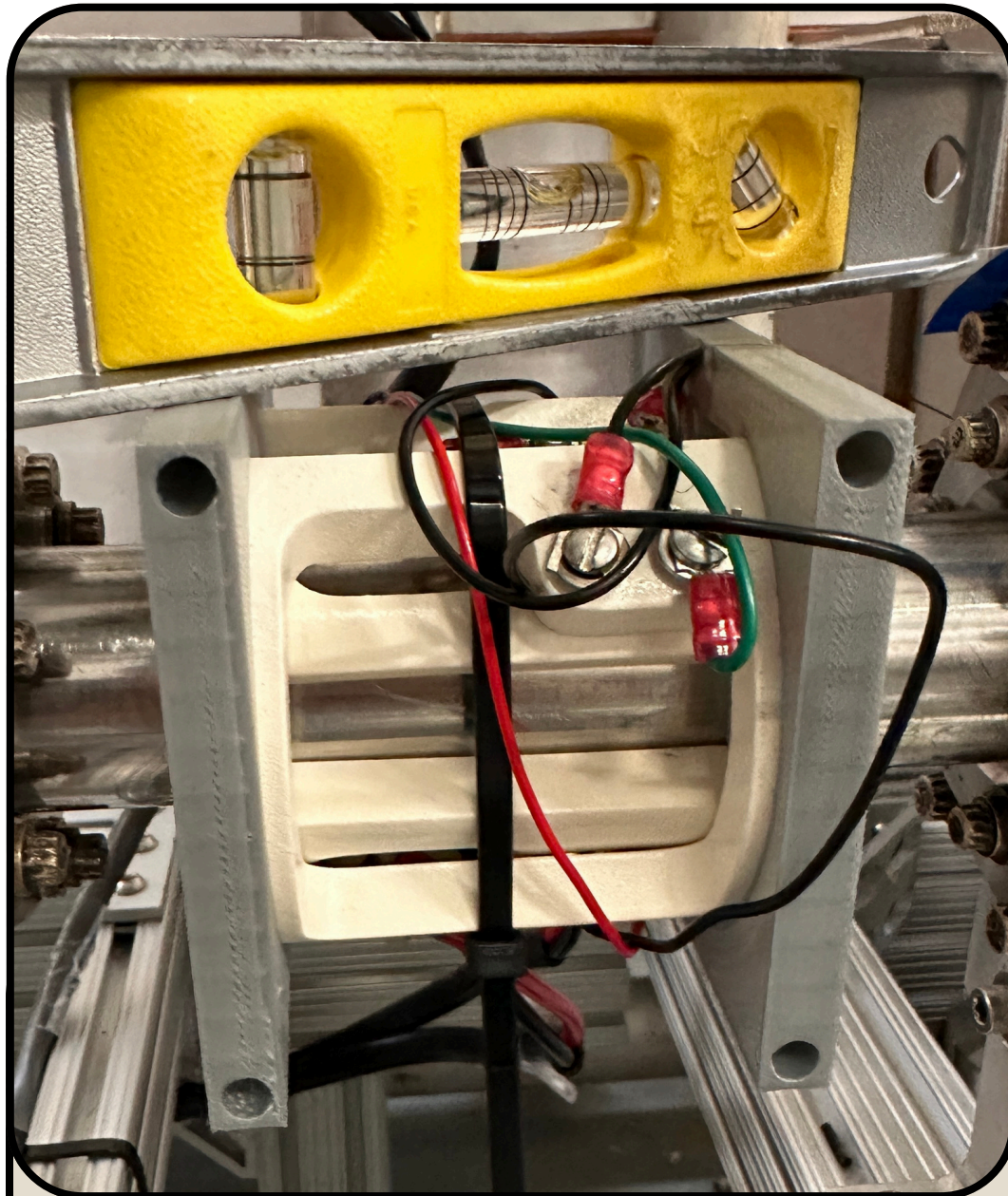
Graphed B-field curve correlating magnetic flux in "tesla" to distance in "cm"

CST Results



- **Parameters**
- **Graph**
- **Calculations**
- **Total Field @ 1 Turn**
 - **1.17 $\mu\text{T m}$**

Installation ✨



Levelling the installed 0150
fixture on UITF

- **Tools**
- **Procedure**
- **Wiring**
- **Initial Testing**
 - **Hall Probe + Bubble Level**



Testing ✨

- **UITF Lockdown Procedure**
- **Beam Visualization (View Screen)**
- **Corrector Magnet Test**
 - **Vertical/Horizontal Shifts**



Tech Notes



Overview

UITF Corrector Magnets 3D-Printed Alignment Fixture Workflow: Design, Fabrication, and Testing

Z. Geadah, M. Bruker

June-July 2024

Abstract

The UITF (Upgraded Injector Test Facility) at Jefferson Lab, demonstrated the need for a well-designed and documented fixture to accurately, efficiently, and precisely align the corrector magnets running along the beam line. Such optimization of the UITF is prohibitively complex when the fabricated parts, machined out of aluminum due to their paramagnetic properties, fail to clamp the corrector magnets reliably. We aim to introduce how 3D modeling, geometric calculations, schematic design, and CST magnetic visualizations can be combined toward this goal, describing the basics of their use and some caveats to be aware of.

1 Introduction

Along the UITF, the corrector magnets aim to counteract the Earth's respective magnetic field. Located at 37.0966° N, 76.4867° W, Jefferson Lab experiences a magnetic declination of approximately 10.76° W $\pm 0.36^\circ$ (changing by 0.01° W per year) and a field strength of 49454.8 nT. The alignment of the corrector magnet allows for a predictable beam path throughout the process, inducing reliable beam results. For optimal performance, two corrector magnets are required for each segment upstream of a solenoid lens, with one magnet to alter the orientation of the beam and another to return the beam to a perfectly horizontal position. Often, only one correct magnet is used which makes for a zigzag-type trajectory, adequate but not ideal. Achieving said result with accuracy and precision is instrumental to the holistic process. The alignment mounts must position the corrector magnets such that they experience no angular deformation off their set horizontal position. Such an angle induces a varying magnetic field throughout the beam pipe, allowing for variability within results.

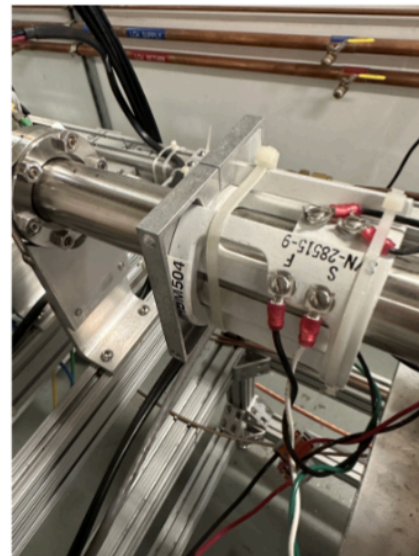


Figure 1: An image of the alignment fixture and corrector magnets

- **Learning LaTeX**
- **Writing Process**
- **Importance/Goals**



Acknowledgments ✨

Summary



- **Special Thanks!**
- **Reflection**
- **Take Away's**
- **Questions**