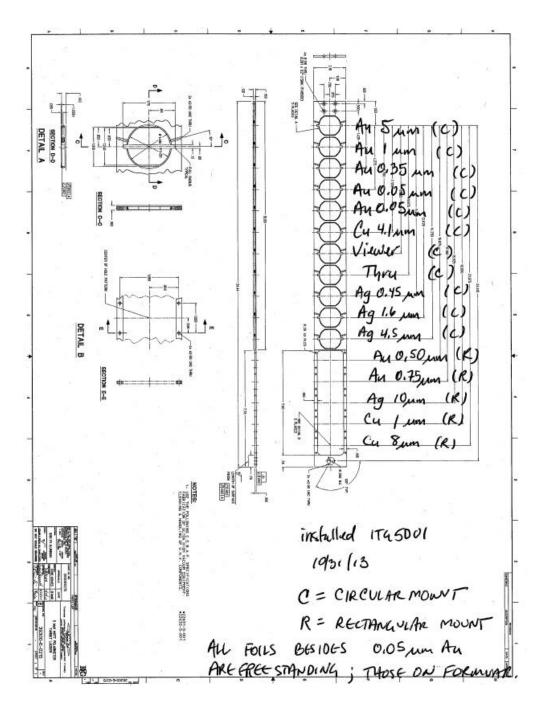
## **Mott Target Ladder for Commissioning**

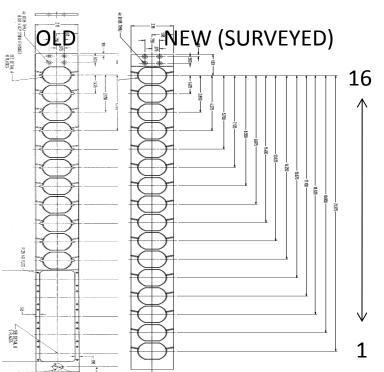
December 20, 2013

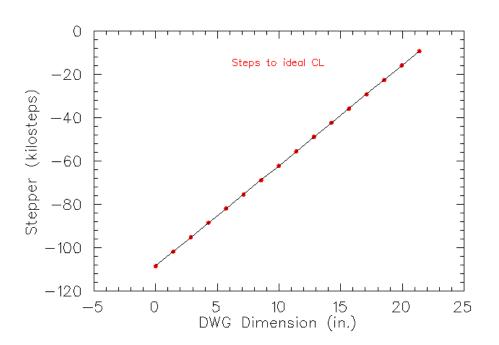


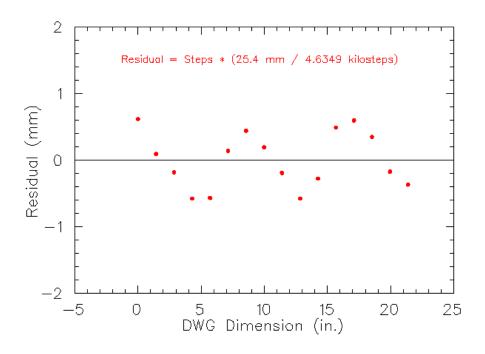
**Downstream Face** 



! Ideal	= 7.90" = Chambe	r CL to target	port flange
POS!	STEPS SURVEY-DT-1527 (#)	DWG 39300-E-0215-R (inches)	EVA
16 15 14 13 11 10 9 8 7 6 5 4 3 2 1	-108535 -101835 -95180 -88503 -81900 -75425 -68875 -62225 -55550 -48875 -42325 -35860 -29275 -22625 -15925	0.000 1.425 2.850 4.275 5.700 7.125 8.550 9.975 11.400 12.825 14.250 15.675 17.100 18.525 19.950 21.375	







# Jefferson Lab Alignment Group

### Data Transmittal

TO: J.Grames DATE: 13 Nov 2013

FROM: Chris Gould Checked: #: L1527

#### **DETAILS:**

M:\align\DATA\Step2B\INJ\131031B

Below are the results of the recent Mott Can and Ladder survey. Locations for the can are reported in CEBAF coordinates and in a beam following system where positive Z is downstream, positive Y is up and a positive X is to the beam left. Locations for the ladder are reported relative to CEBAF coordinates, beam following and relative to the MOTT Can. Yaw angles are given relative to ideal and are reported in degrees. A positive Yaw angle is counter-clockwise from above, a positive pitch angle is counter-clockwise from the beam right side and a positive roll angle is clockwise looking downstream. The step count for the ideal position of each target is also given where target 1 is the bottom most target and 16 is the top most target. It should also be noted that while fiducializing the target ladder 6 degrees of backlash in the yaw direction was observed.

	CEBAF COORDS (M)			BEAM FOLLOWING(mm)									
	Z	х	Υ	Z	Х	Y	dYaw	dPitch	dRo	II			
TARGET CAN	-241.11774	81.05479	99.99963	-3.652	-0.29	-0.367	0.0	0.0	-0.	1			
	CEBAF COORDS (M)		BEAM FOLLOWING(mm) d		dYaw	dPitch	dRo	JV	RELATIVE	то мотт с	AN(mm)		
	Z	х	Υ	Z	Х	Υ					Z	х	Υ
TARGET LADDER	-241.11786	81.05602	99.999813	-3.514	0.938	-0.187	-0.4	0.1	0.	2	0.11	1.25	0.2
•		•											

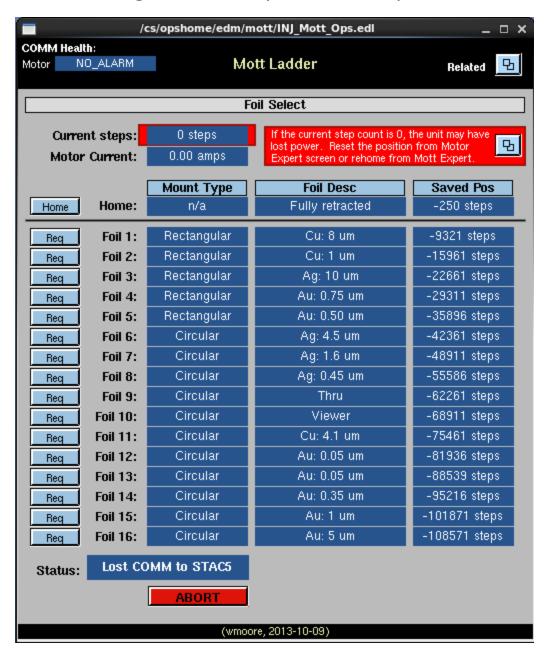
Ladder is +0.2 mm high relative to Mott can, so all targets need to be inserted 0.2 mm further.

This translates into (4.6349 kilosteps / 25.4 mm) \* 0.2 mm = 36 steps

Note 1: This means stepper changes from X to X-36

Note 2: error on linear fit is 38 steps

#### Target Ladder Expert Values Updated



#### FSD Bit Tested (Motion = Fault)

