

# Fast Helicity Reversal

*Riad Suleiman*

Injector Group

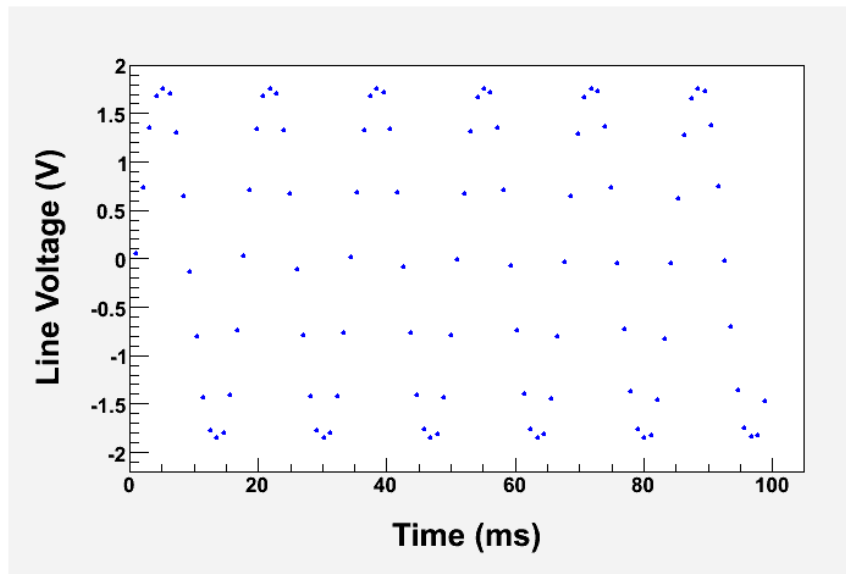
June 2, 2009

# Outline

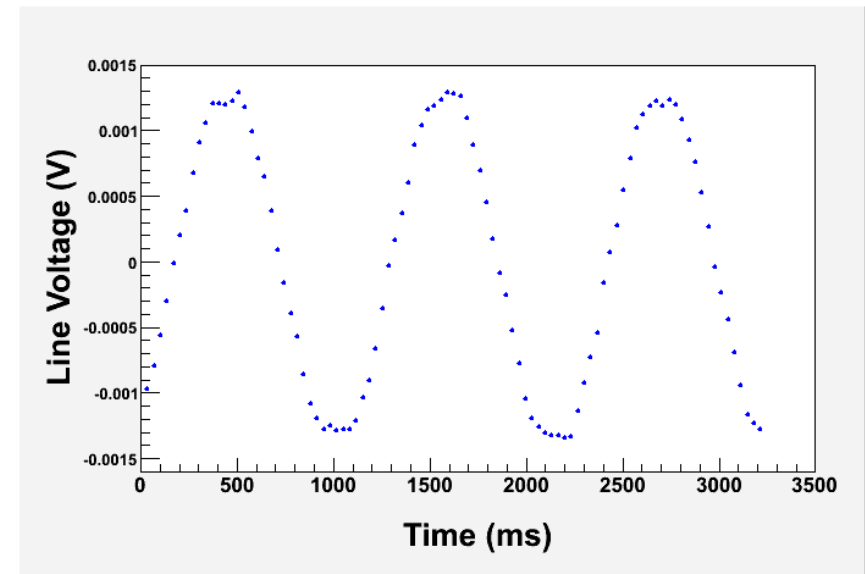
- Why Changing Helicity Reversal Rate?
  - ✓ Reduce Noise Contributions to Measurement Error
- PQB at 30 Hz Helicity Reversal
- PQB at 1 kHz Helicity Reversal
  - ✓ Charge Asymmetry
  - ✓ Position Differences
  - ✓ Charge Asymmetry Separation
- How to Reduce 60 Hz Line Noise with Fast Helicity Reversal?
- Summary

# Now at 30 Hz Reversal, Why?

- Power line 60 Hz frequency is major source of noise in parity experiments
- For 30 Hz reversal,  $T\_Stable$  (= 33.333 ms) contains exactly two cycles of 60 Hz line noise → by design, this reversal cancels line noise



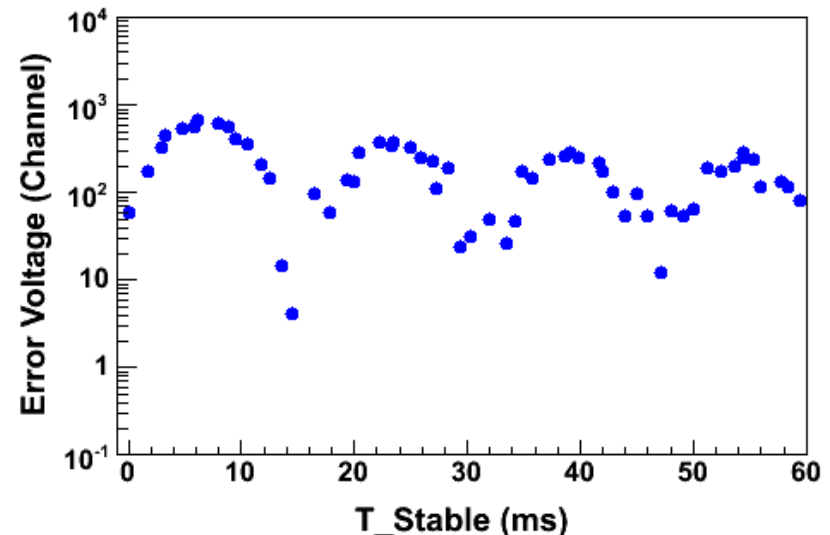
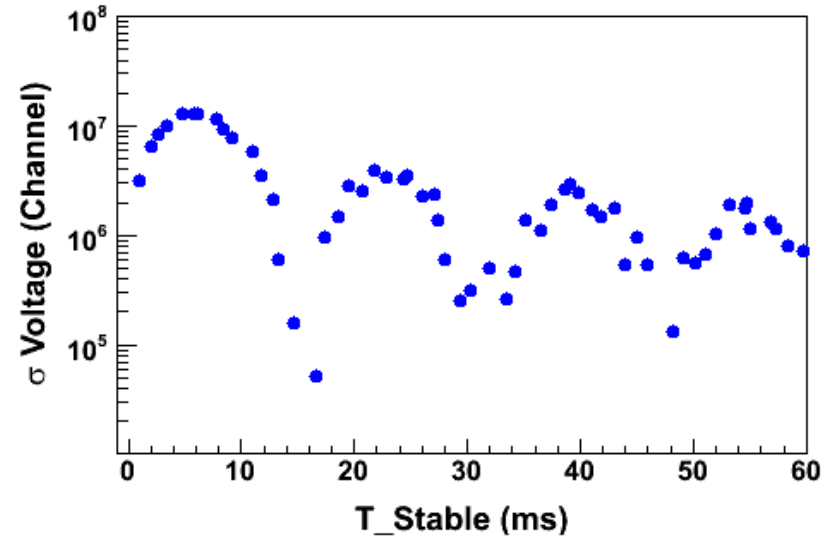
$T\_Stable = 0.980$  ms



$T\_Stable = 33.333$  ms

# Widths and Errors, 60 Hz Noise

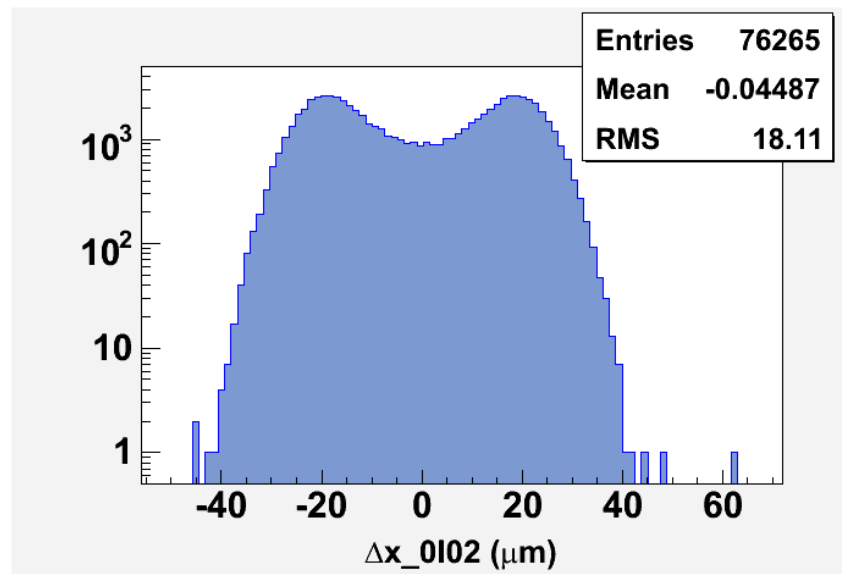
- 60 Hz line noise cancels at:
- I. Small  $T_{\text{Stable}}$
  - II.  $T_{\text{Stable}} = 16.667$  ms
  - III.  $T_{\text{Stable}} = 33.333$  ms
  - IV. ...



Note: Noise increases width of distributions  $\rightarrow$  increases error on the mean,  $\sigma/\sqrt{N}$ , where  $N$  no. of data points. However, it does not change the mean.

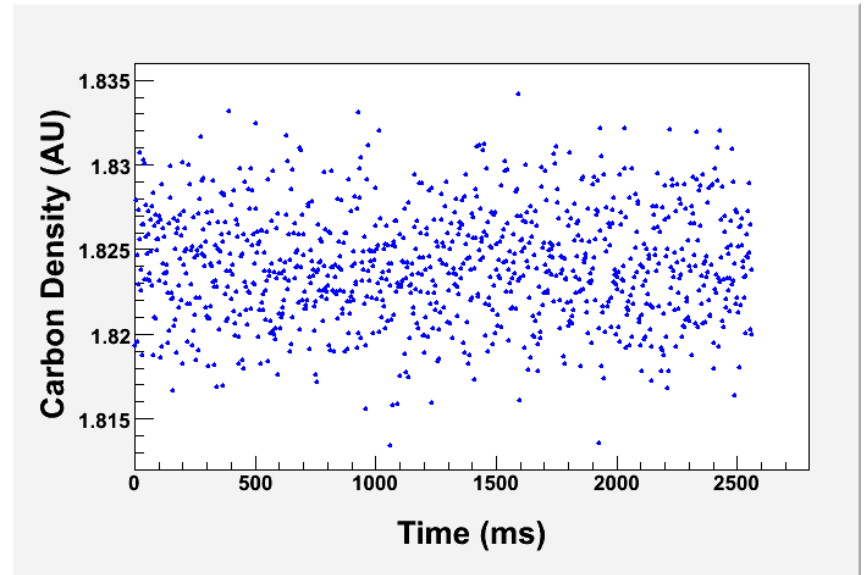
# Need Fast Reversal, Why?

- Problem:
  - There are other sources of noise at low frequencies, *i.e.*, target density fluctuations, PSS Current Sensor, ...
- Cause larger widths of helicity correlated distributions, double-horned distributions, ...

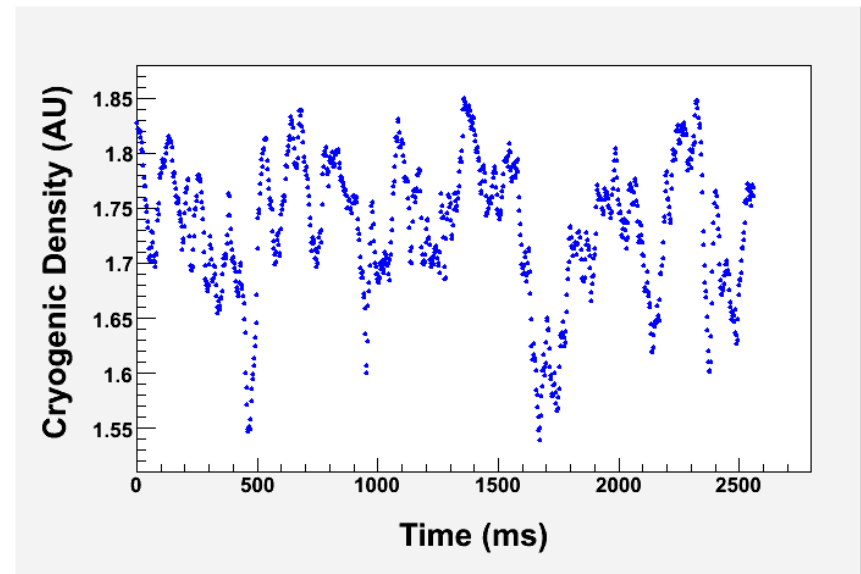


# Target Density Fluctuations

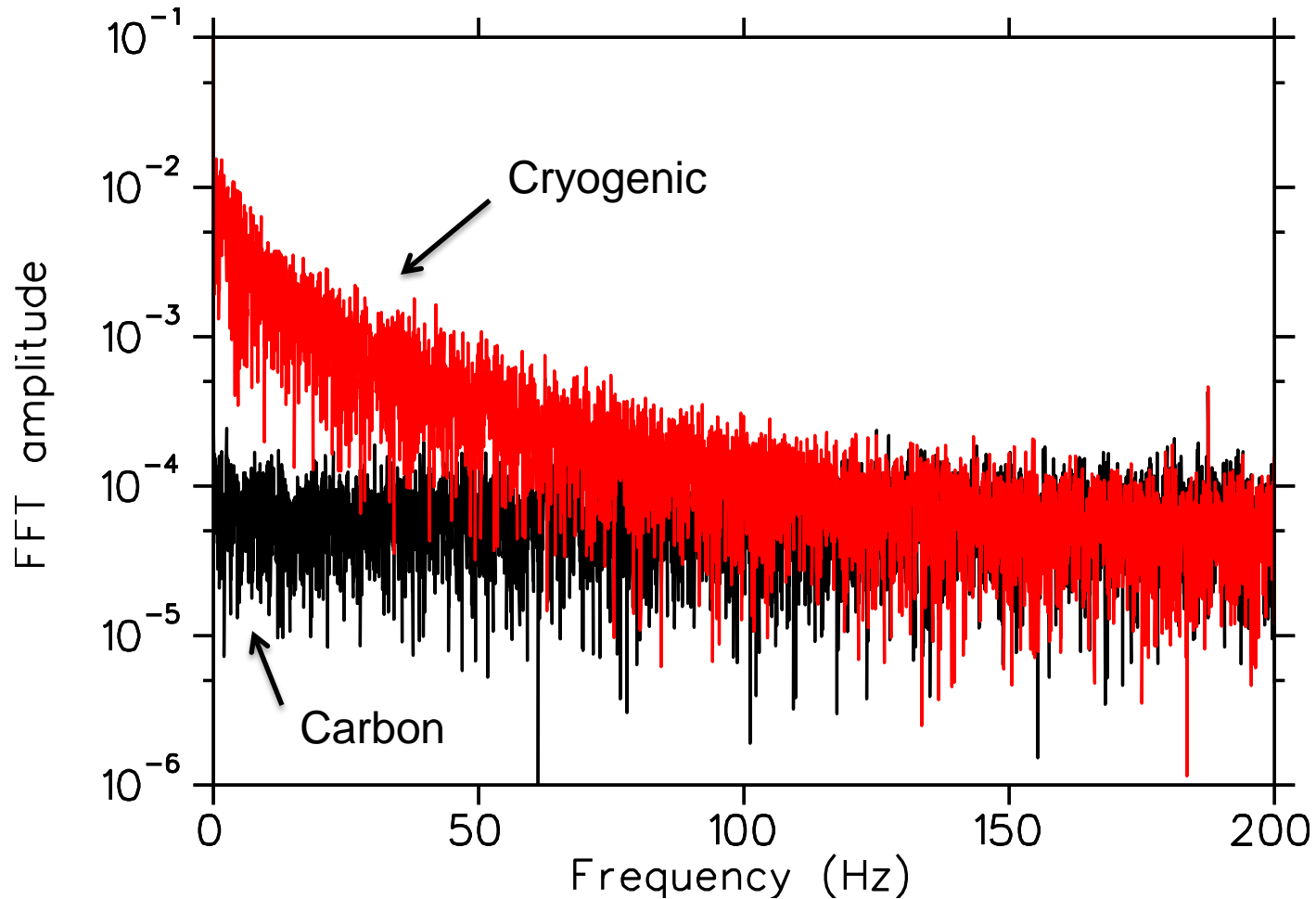
- ✓ Carbon target has only statistical fluctuations – no boiling



- ✓ Cryogenic target boils when heated by electron beam. For QWeak: 180  $\mu$ A on 35 cm liquid hydrogen target (2.5 kW heat load)

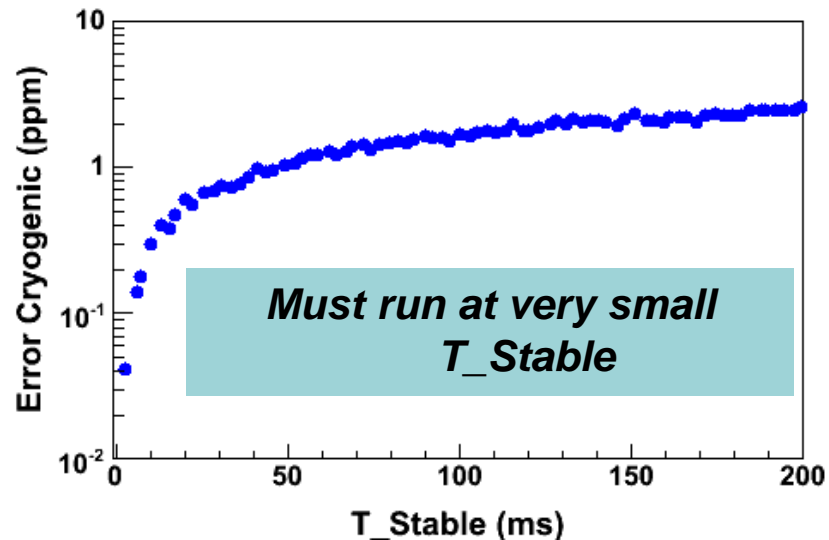
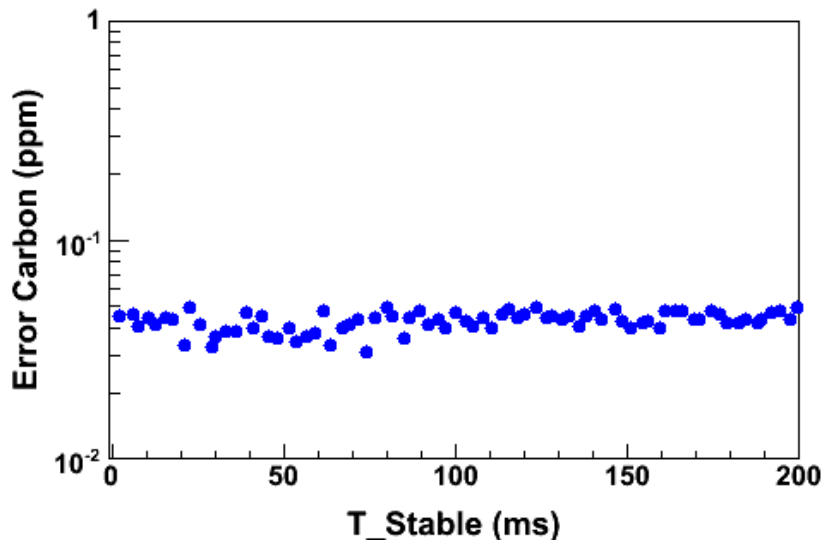
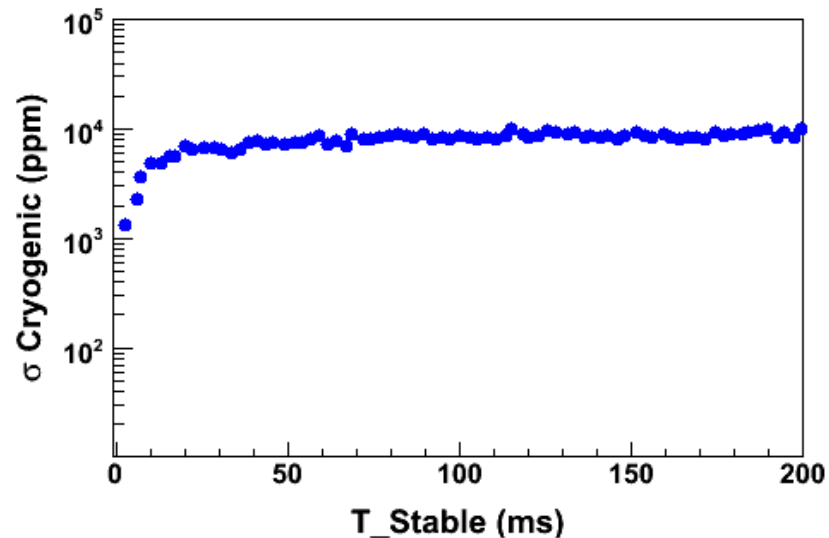
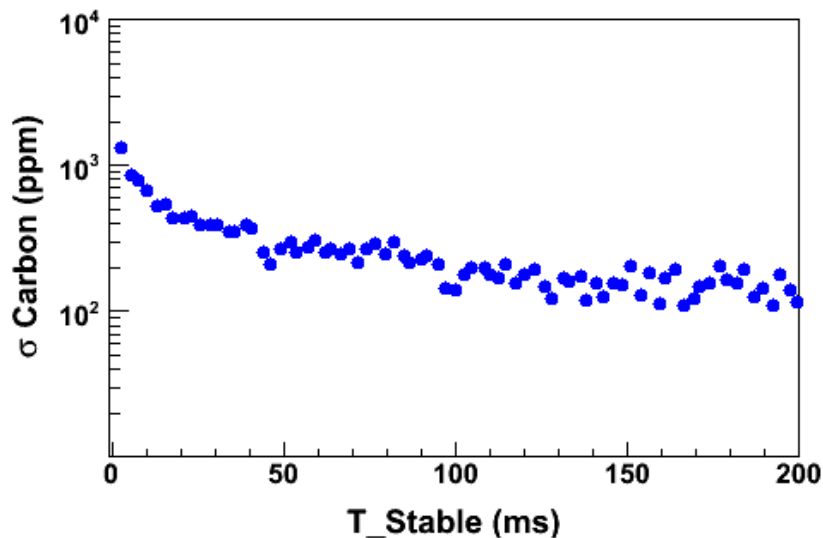


# Fast Fourier Transform (FFT) of Target Density



# Widths and Errors

*For Errors, assume 1 month long experiment*

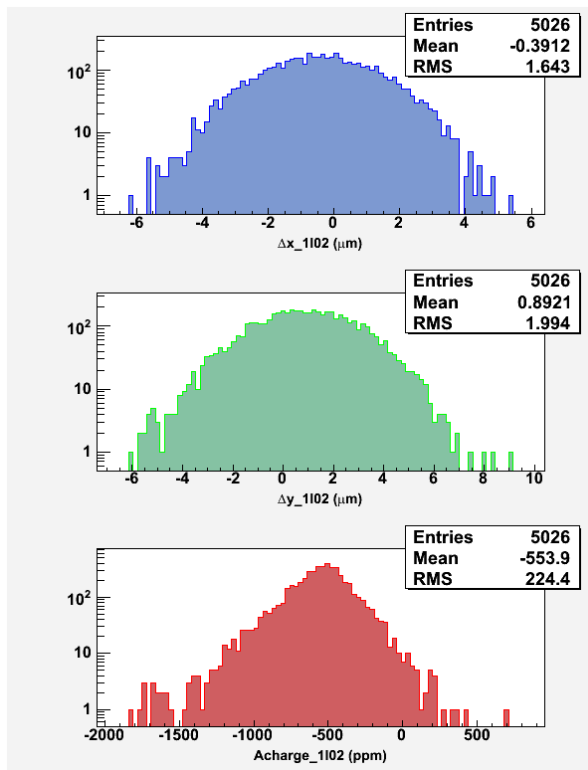




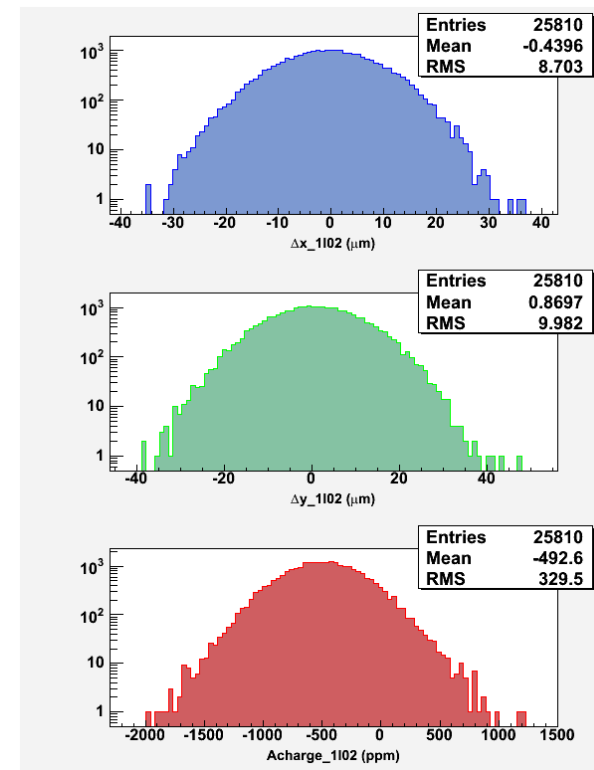
# Widths at 1 kHz and 30 Hz

Note: For statistical (white) noise, the increase in width going

from 30 Hz to 1 kHz is:  $\sqrt{\frac{33.333}{0.980}} = 5.8$



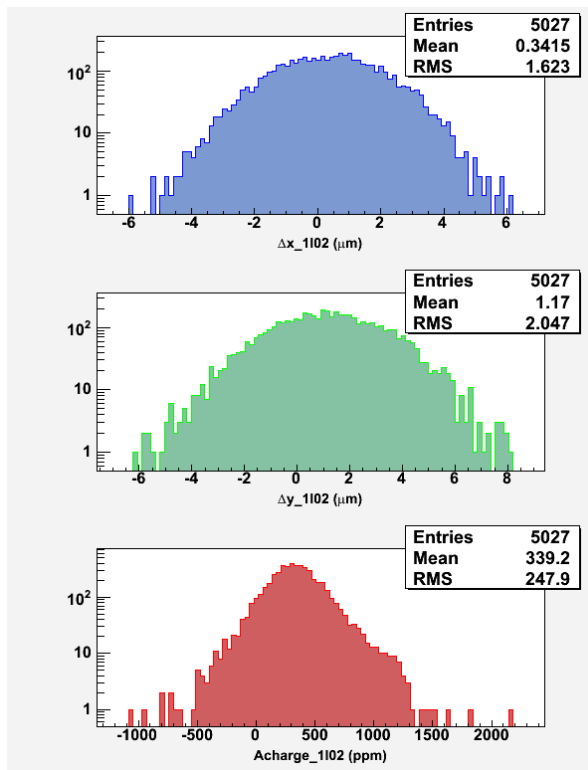
**30 Hz,  $T_{\text{Stable}} = 33.333$  ms,  
 $T_{\text{Settle}} = 500$   $\mu\text{s}$ , OUT**



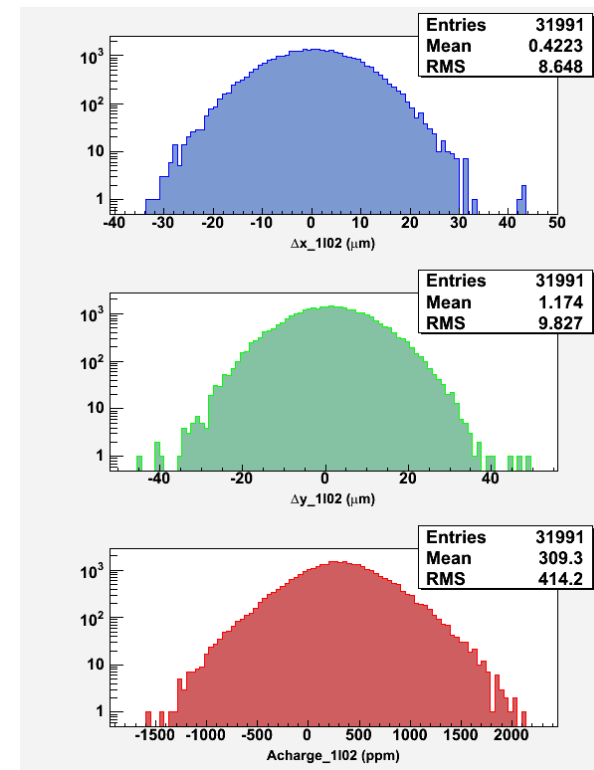
**1 kHz,  $T_{\text{Stable}} = 0.980$  ms,  
 $T_{\text{Settle}} = 60$   $\mu\text{s}$ , OUT**

## Note:

- ✓ No significant noise reduction for position differences
- ✓ Factor of 3 noise reduction for charge asymmetry width



**30 Hz,  $T_{\text{Stable}} = 33.333$  ms,  
 $T_{\text{Settle}} = 500$   $\mu\text{s}$ , IN**

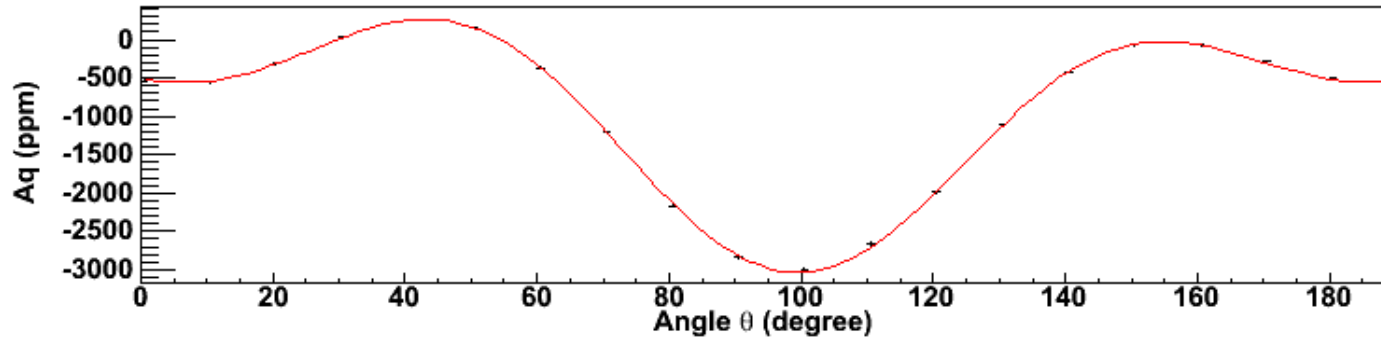


**1 kHz,  $T_{\text{Stable}} = 0.980$  ms,  
 $T_{\text{Settle}} = 60$   $\mu\text{s}$ , IN**

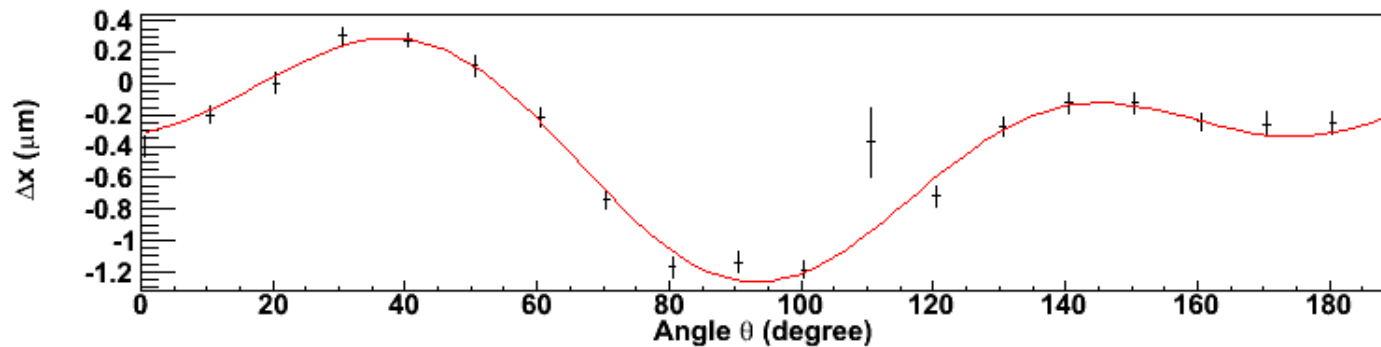
PQB

30 Hz Reversal, 500  $\mu$ s

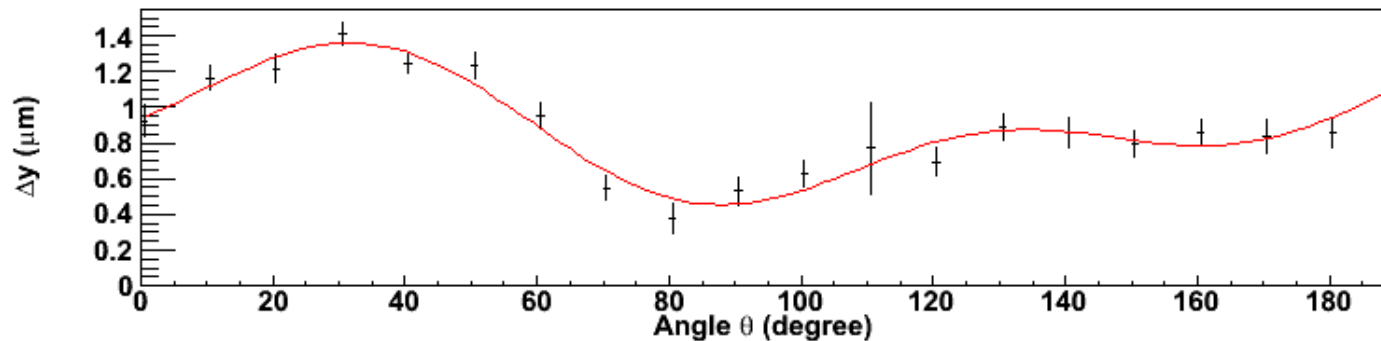
# Run 689, PITA = 0, IHWP OUT, ILP OUT, QWK\_1102



$$A_q = -952.43 + 1252.02 \sin(2\theta + 65.86) + -841.07 \sin(4\theta + 66.39)$$

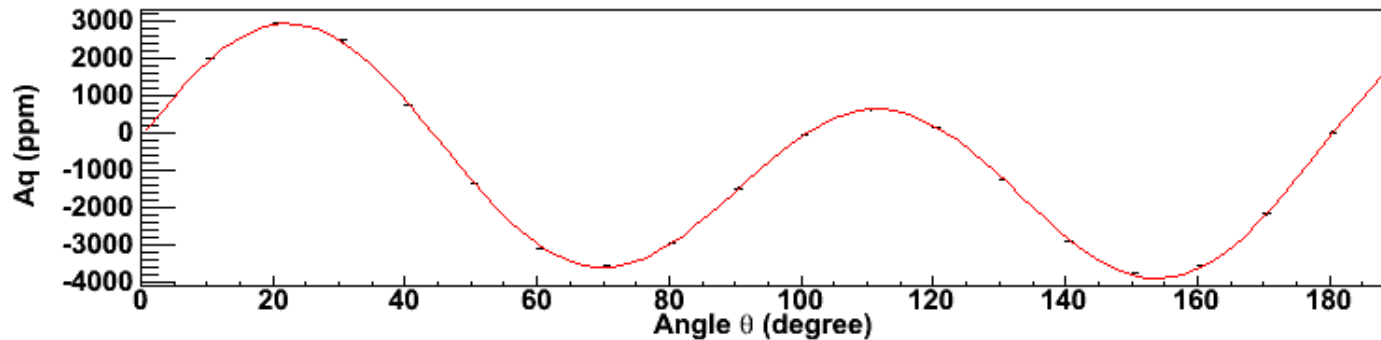


$$\Delta x = -0.39 + 0.52 \sin(2\theta + 64.99) + -0.40 \sin(4\theta + 89.46)$$

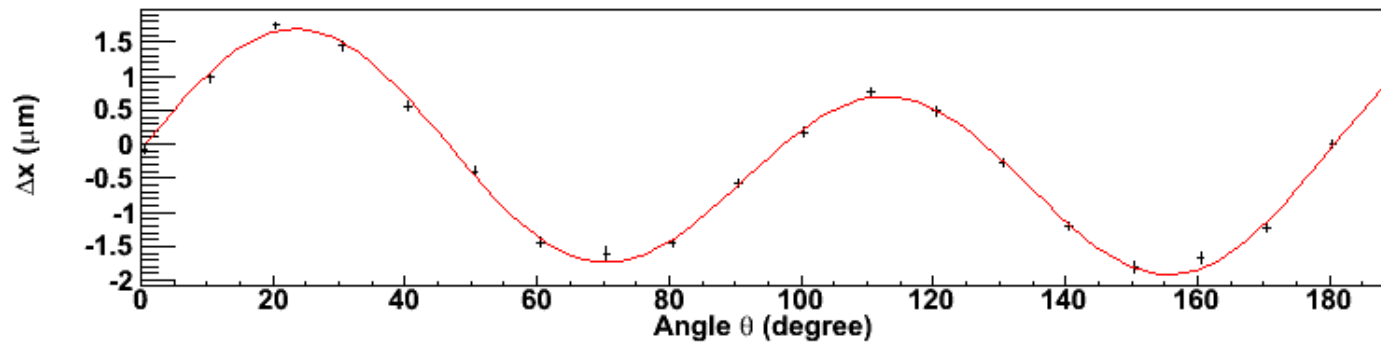


$$\Delta y = 0.88 + 0.30 \sin(2\theta + 52.80) + -0.22 \sin(4\theta + 125.73)$$

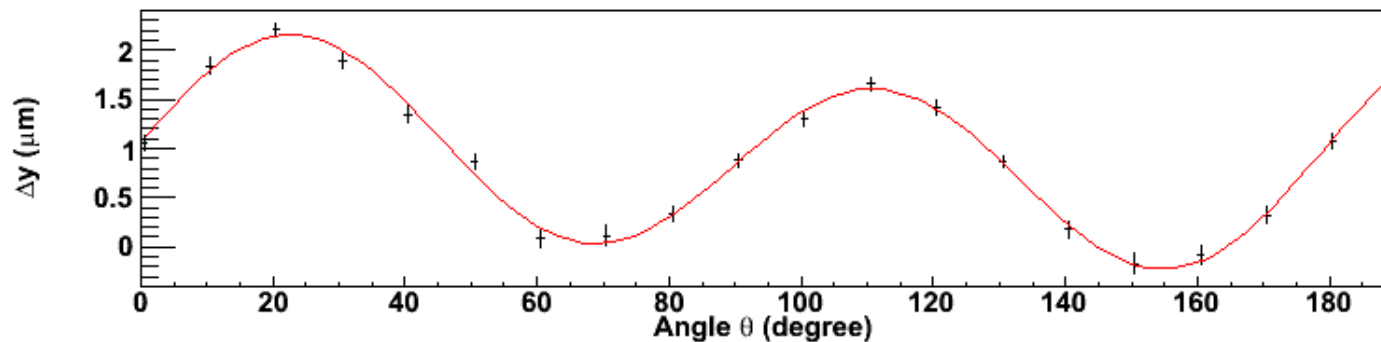
# Run 690, PITA = -120, IHWP OUT, ILP OUT, QWK\_1102



$$A_q = -938.92 + 1160.79 \sin(2\theta + 38.98) + 2740.88 \sin(4\theta + 12.66)$$

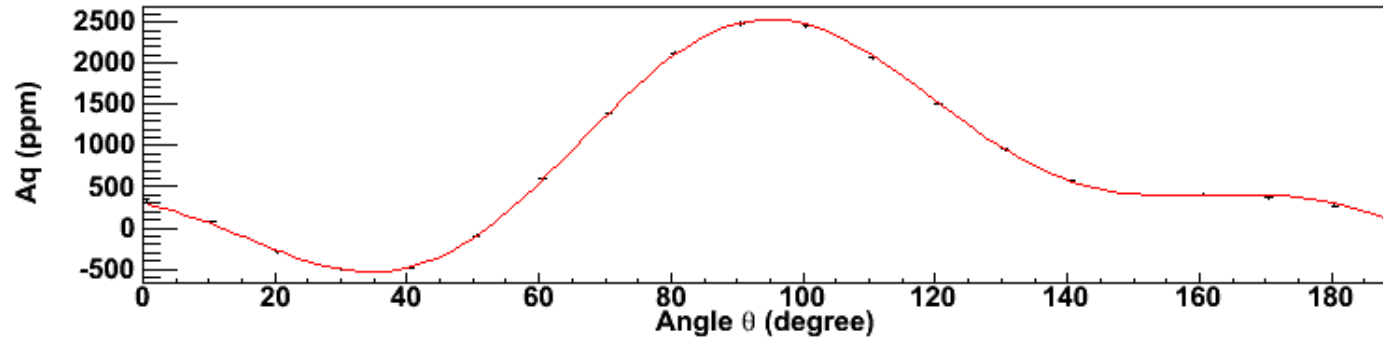


$$\Delta x = -0.30 + 0.50 \sin(2\theta + 33.64) + -1.50 \sin(4\theta + 177.87)$$

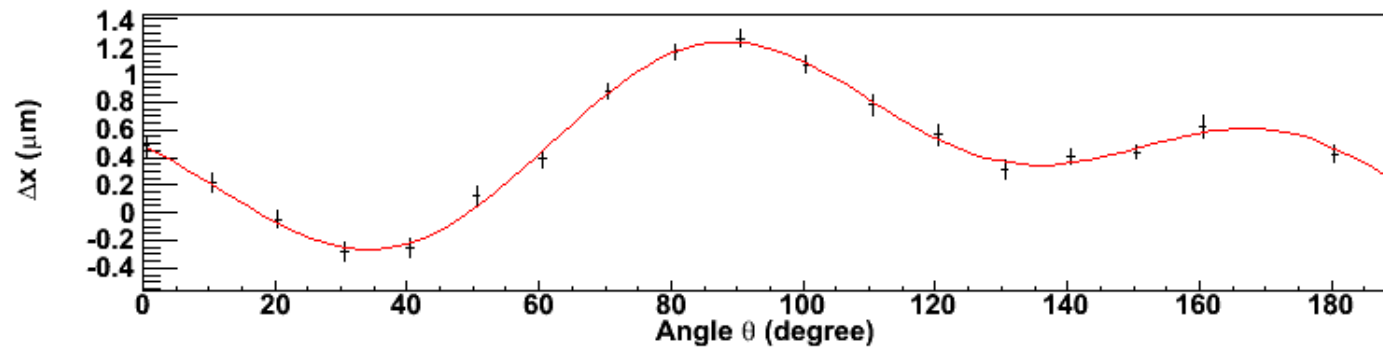


$$\Delta y = 0.90 + 0.30 \sin(2\theta + 21.32) + 0.98 \sin(4\theta + 3.05)$$

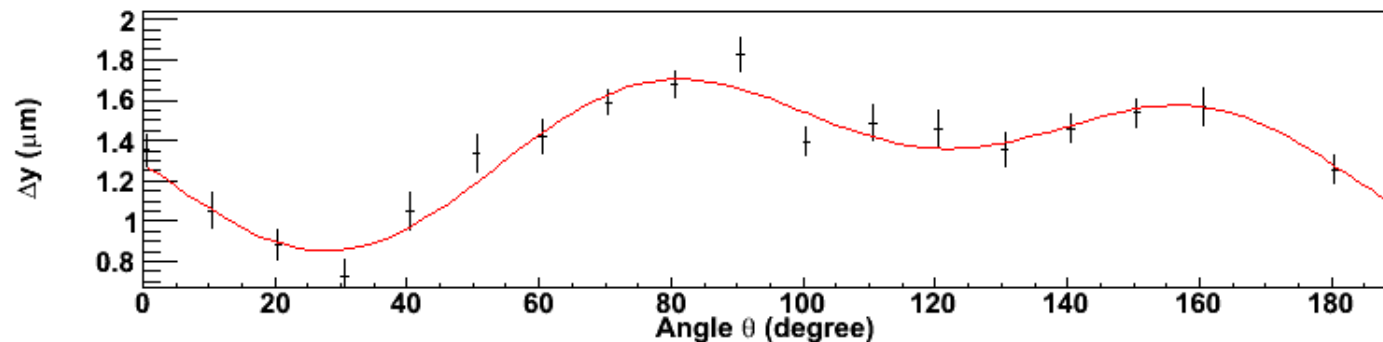
# Run 691, PITA = 0, IHWP IN, ILP OUT, QWK\_1102



$$A_q = 799.62 + -1220.48 \sin(2\theta + 63.16) + 595.06 \sin(4\theta + 97.69)$$

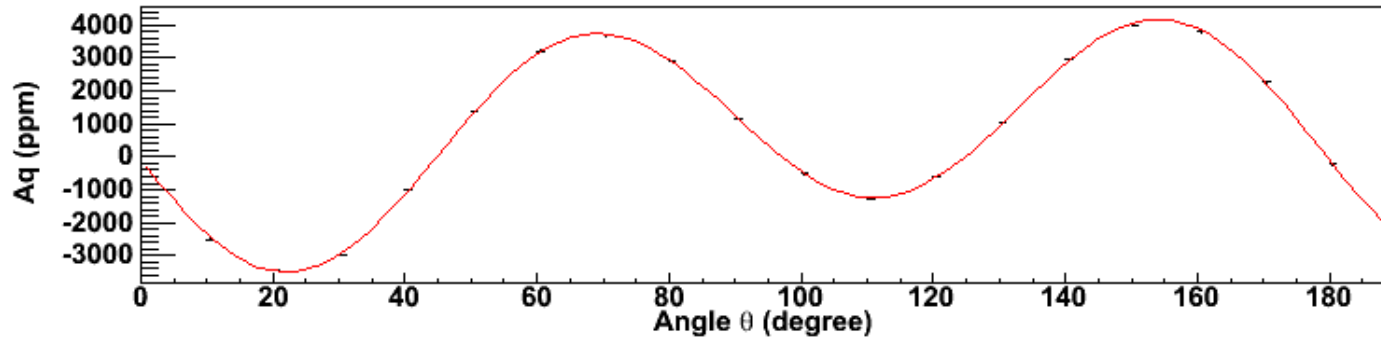


$$\Delta x = 0.48 + -0.45 \sin(2\theta + 57.87) + 0.41 \sin(4\theta + 114.58)$$

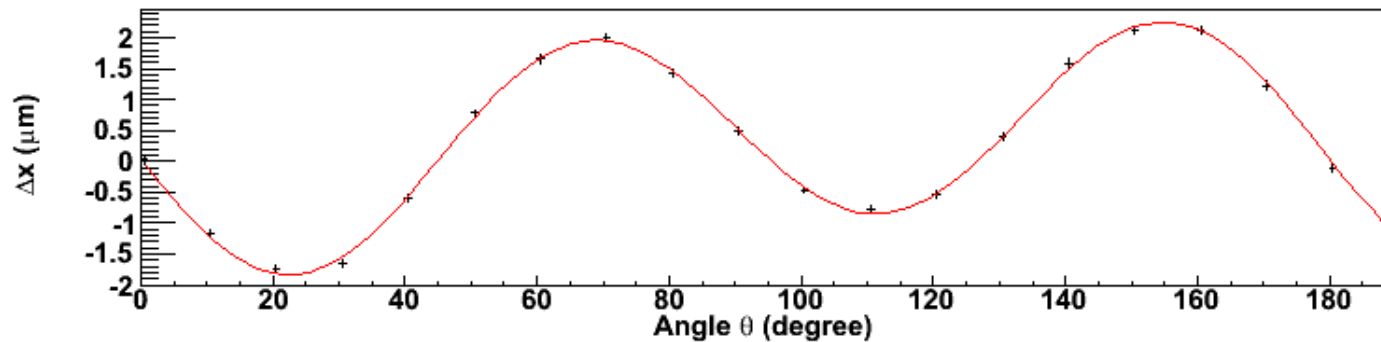


$$\Delta y = 1.36 + -0.26 \sin(2\theta + 46.04) + 0.25 \sin(4\theta + 152.48)$$

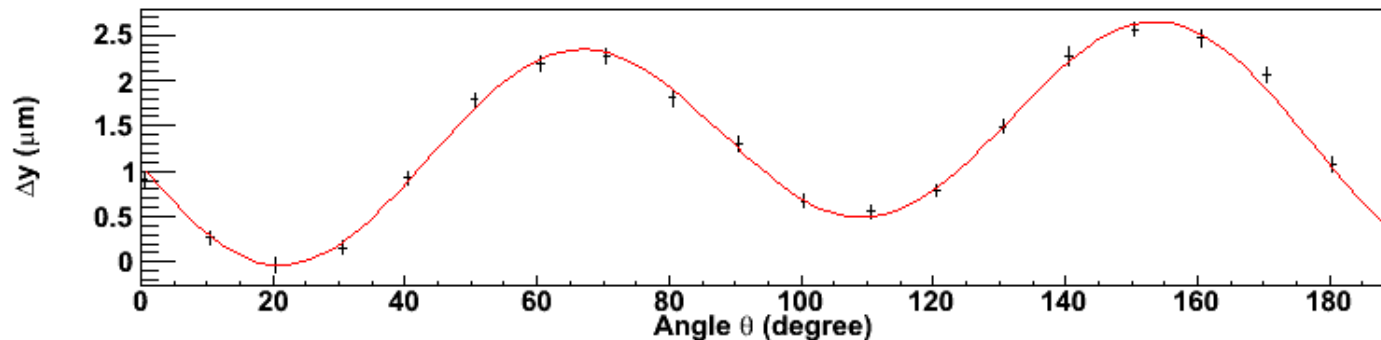
# Run 692, PITA = -120, IHWP IN, ILP OUT, QWK\_1102



$$Aq = 776.38 + -1145.43 \sin(2\theta + 36.03) + -3131.25 \sin(4\theta + 13.94)$$



$$\Delta x = 0.38 + -0.51 \sin(2\theta + 29.90) + -1.71 \sin(4\theta + 2.77)$$



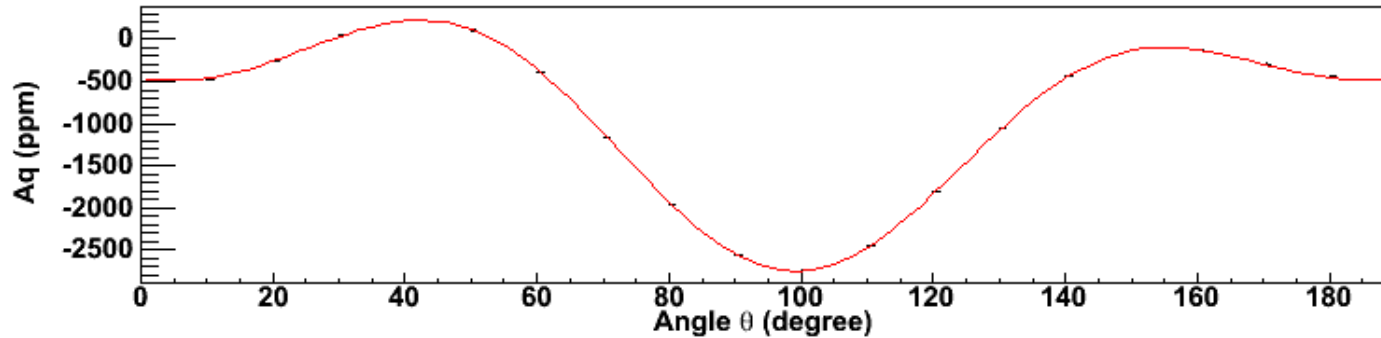
$$\Delta y = 1.36 + -0.30 \sin(2\theta + 19.77) + -1.13 \sin(4\theta + 9.48)$$

PQB

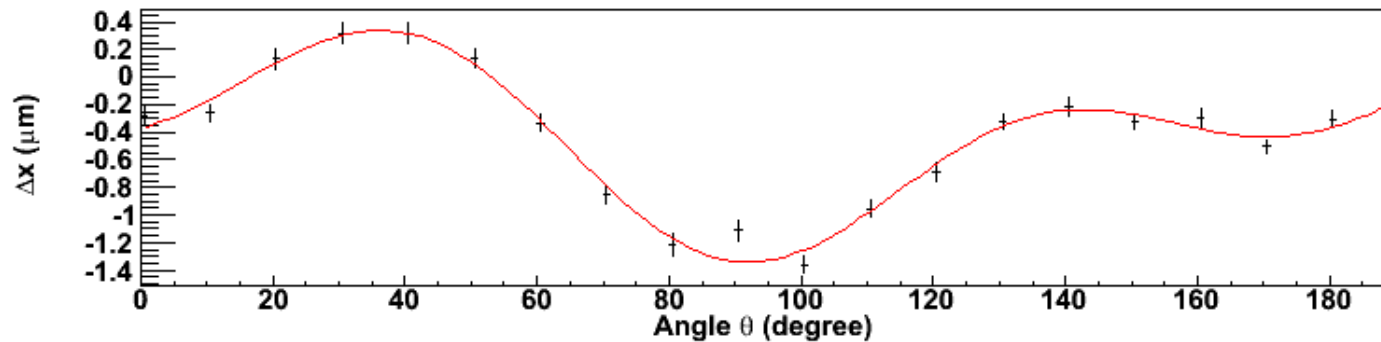
1 kHz Reversal, 60  $\mu$ s



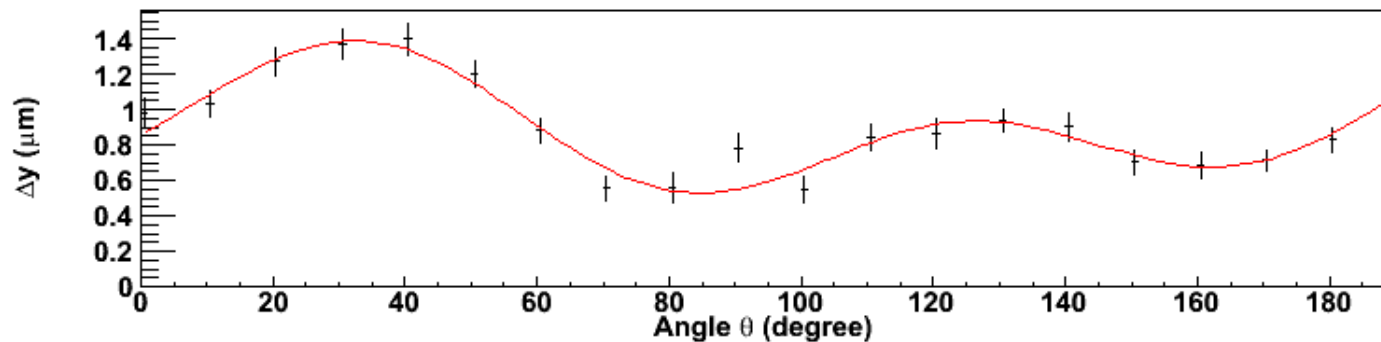
# Run 719, PITA = 0, IHWP OUT, ILP OUT, QWK\_1102



$$A_q = -882.51 + 1146.30 \sin(2\theta + 65.43) + -726.68 \sin(4\theta + 68.60)$$

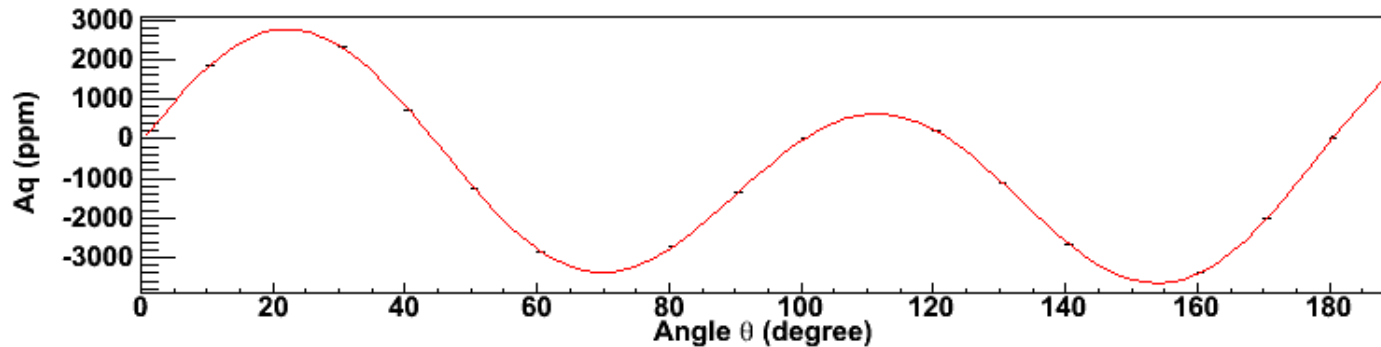


$$\Delta x = -0.44 + 0.55 \sin(2\theta + 61.11) + -0.42 \sin(4\theta + 98.24)$$

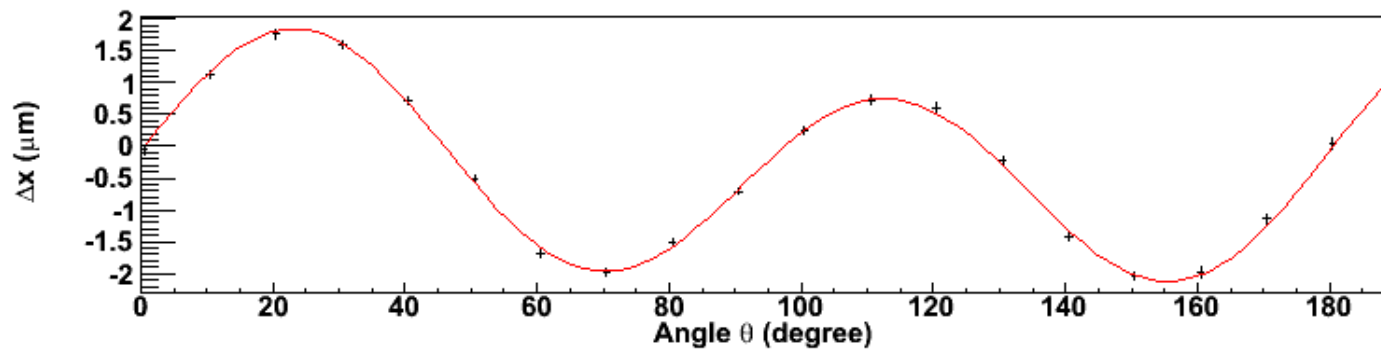


$$\Delta y = 0.89 + 0.24 \sin(2\theta + 40.39) + -0.27 \sin(4\theta + 134.21)$$

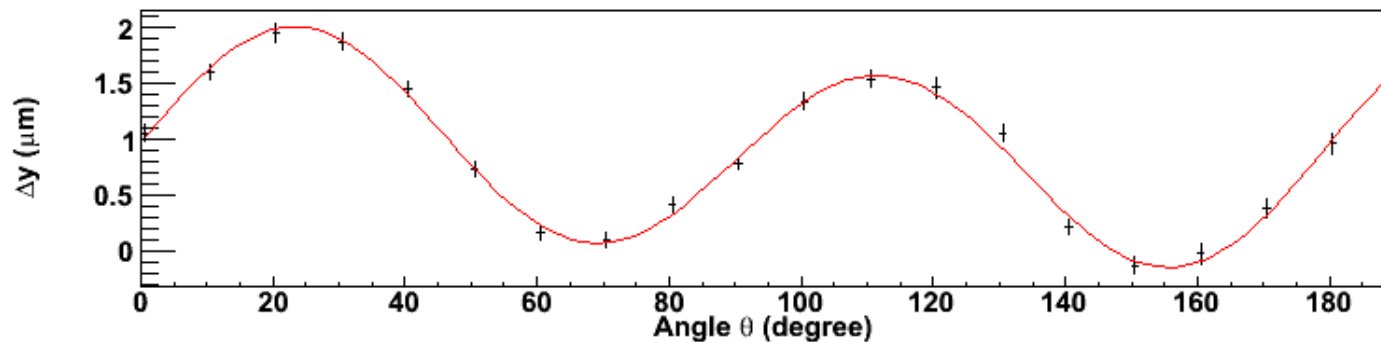
# Run 720, PITA = -120, IHWP OUT, ILP OUT, QWK\_1102



$$A_q = -878.34 + 1073.63 \sin(2\theta + 38.71) + 2578.10 \sin(4\theta + 12.83)$$

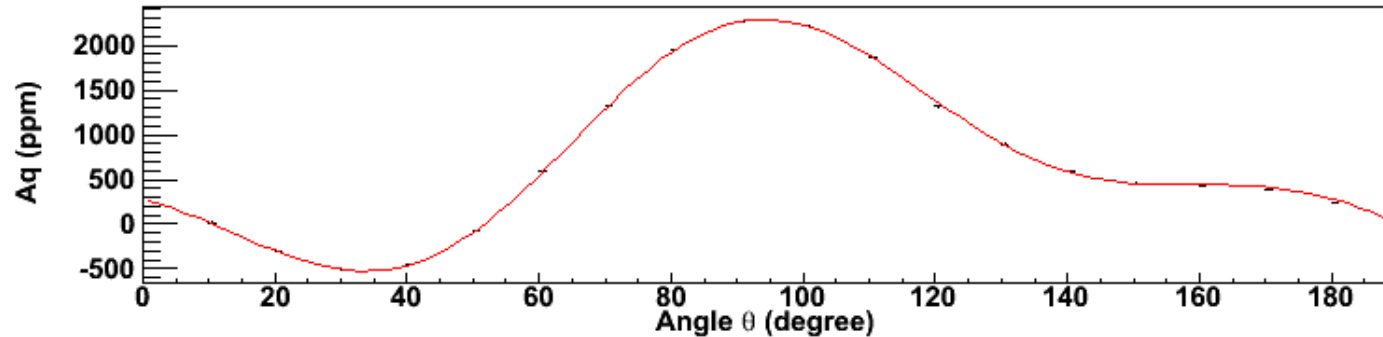


$$\Delta x = -0.36 + 0.55 \sin(2\theta + 36.13) + -1.66 \sin(4\theta + 178.68)$$

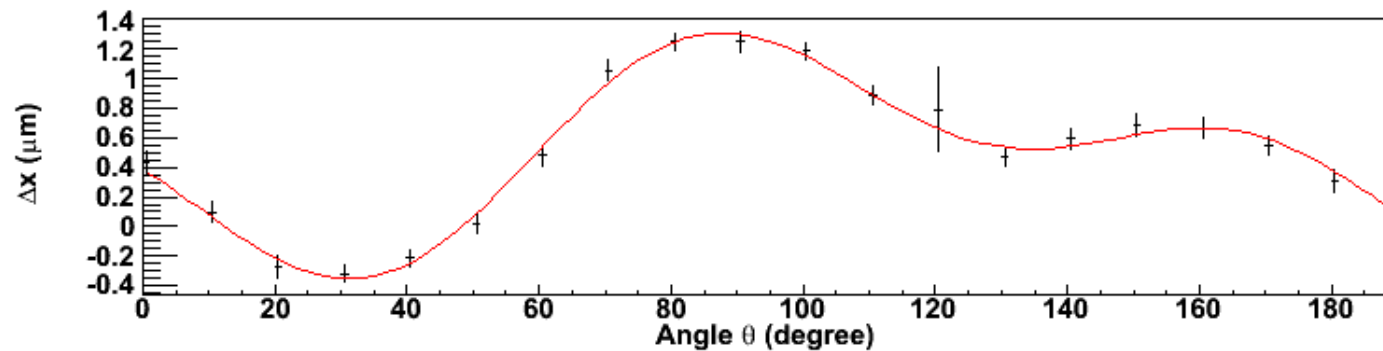


$$\Delta y = 0.88 + 0.24 \sin(2\theta + 18.61) + 0.91 \sin(4\theta + 0.57)$$

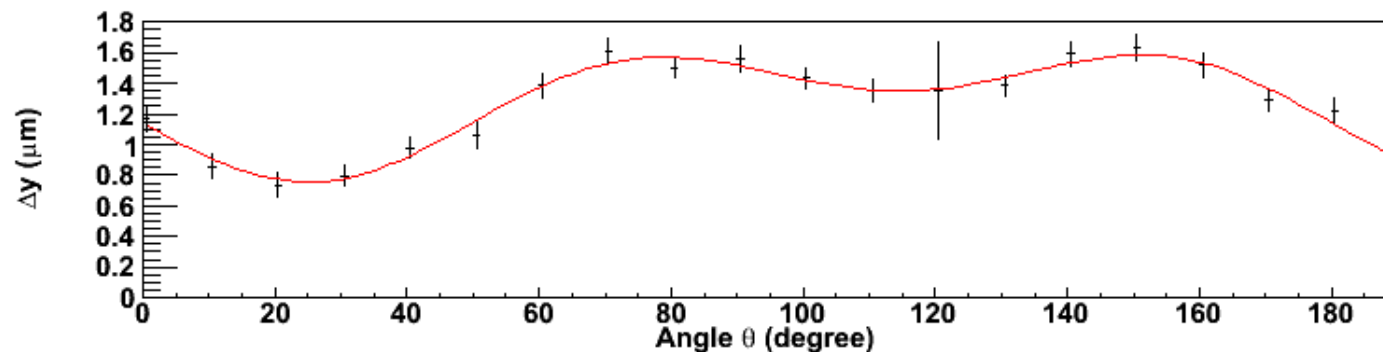
# Run 717, PITA = 0, IHWP IN, ILP OUT, QWK\_1102



$$A_q = 736.66 + -1116.76 \sin(2\theta + 62.29) + 535.61 \sin(4\theta + 103.86)$$

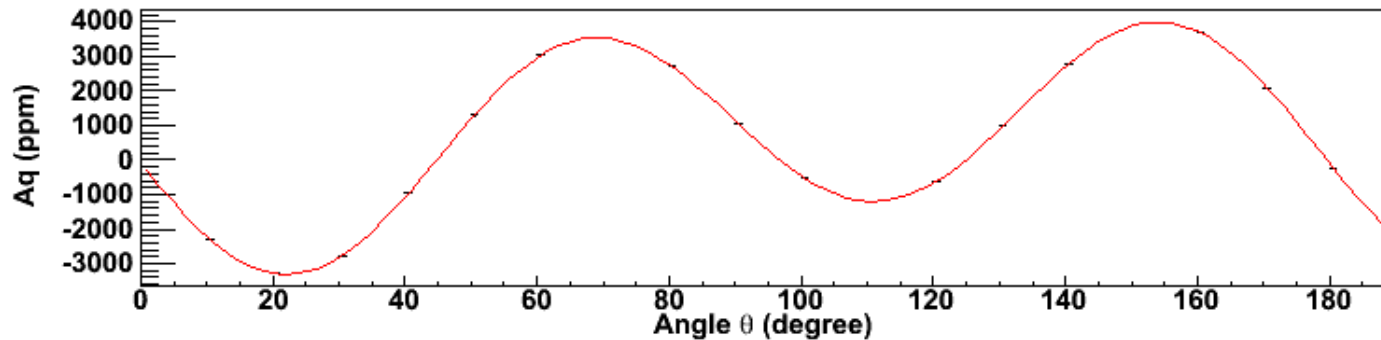


$$\Delta x = 0.52 + -0.56 \sin(2\theta + 54.86) + 0.40 \sin(4\theta + 126.11)$$

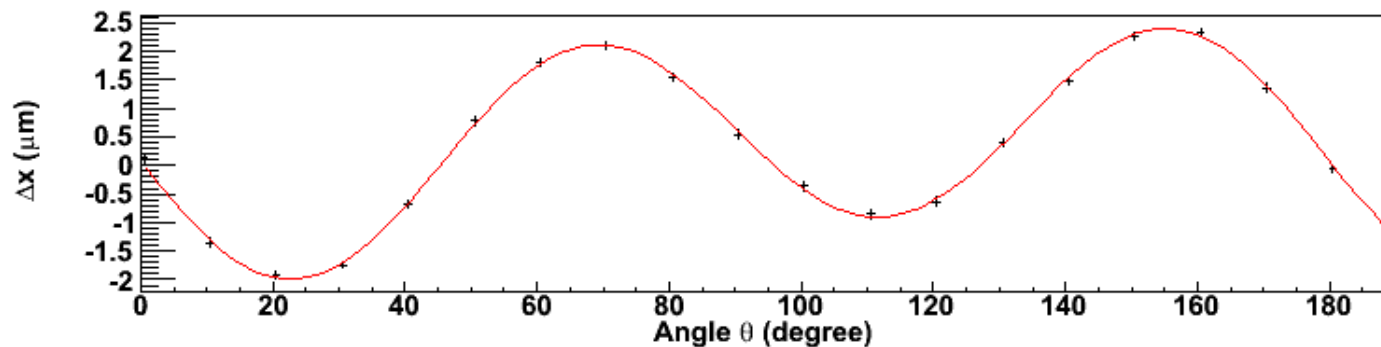


$$\Delta y = 1.29 + -0.30 \sin(2\theta + 39.10) + 0.24 \sin(4\theta + 170.90)$$

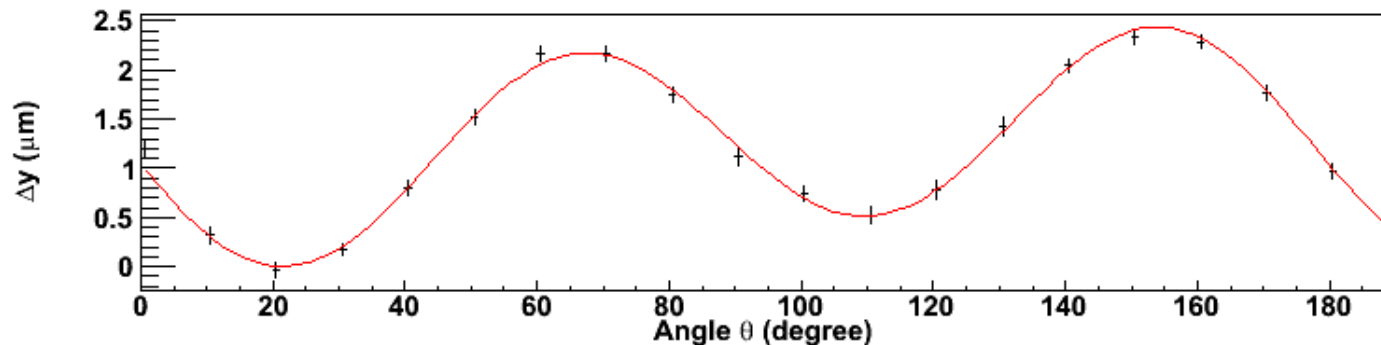
# Run 718, PITA = -120, IHWP IN, ILP OUT, QWK\_1102



$$Aq = 734.01 + -1077.36 \sin(2\theta + 35.12) + -2988.61 \sin(4\theta + 14.19)$$



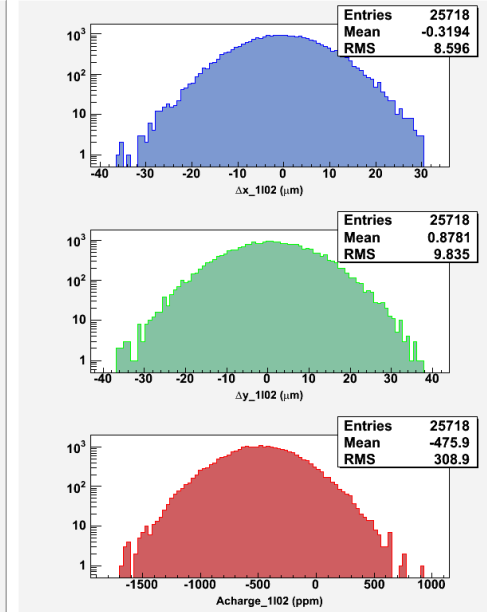
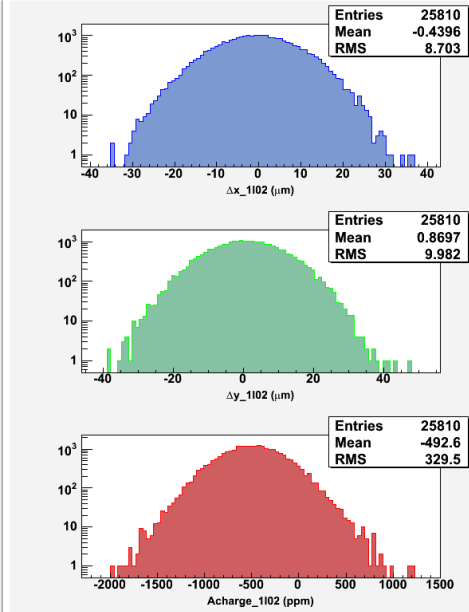
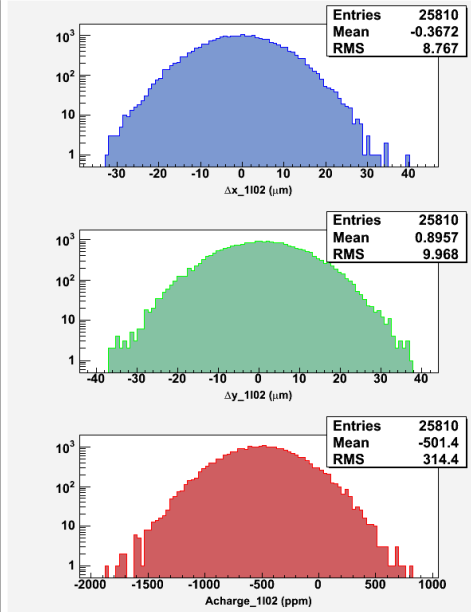
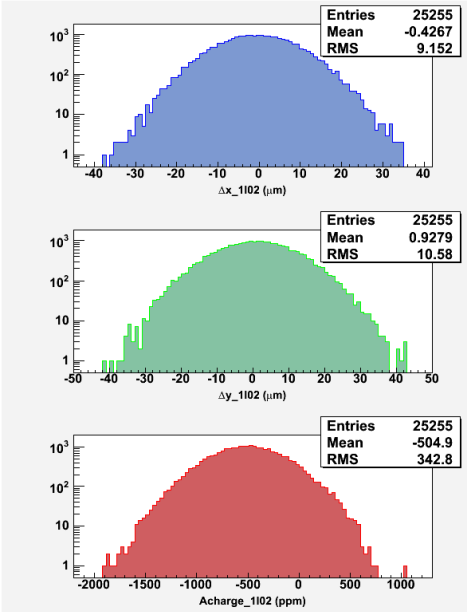
$$\Delta x = 0.39 + -0.56 \sin(2\theta + 30.46) + -1.84 \sin(4\theta + 1.20)$$



$$\Delta y = 1.28 + -0.29 \sin(2\theta + 21.21) + -1.02 \sin(4\theta + 7.62)$$

PQB

1 kHz Reversal, Different choices of  
T\_Settle



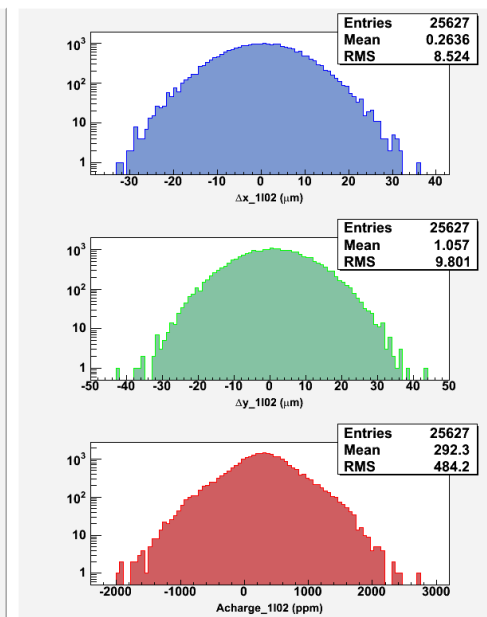
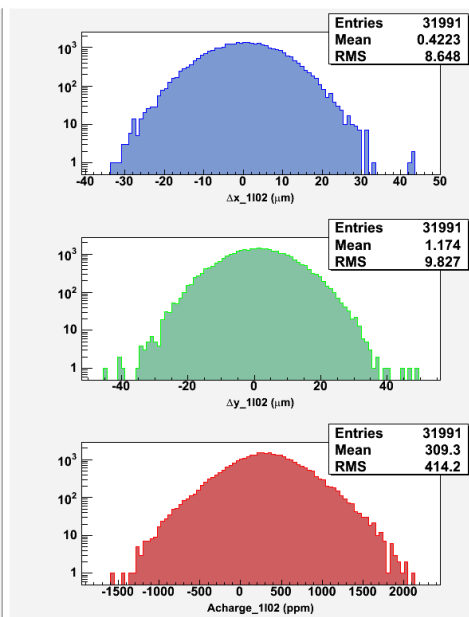
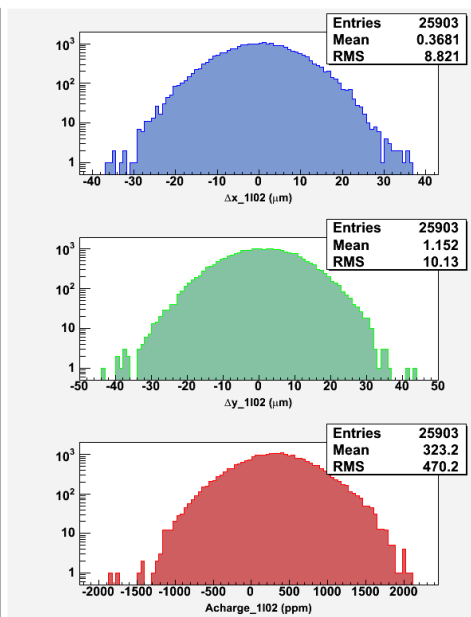
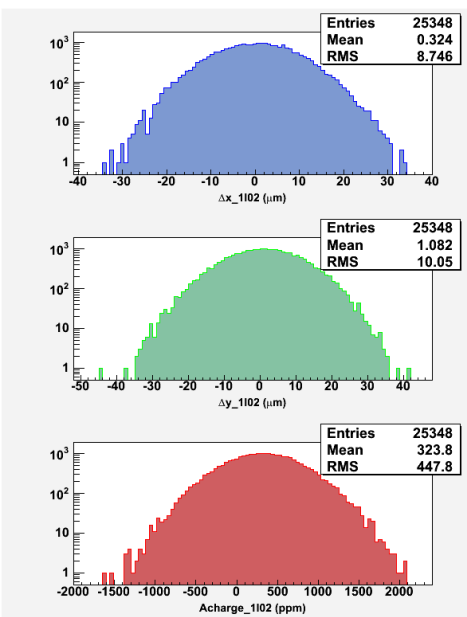
**1 kHz, 500 μs, OUT**

**100 μs**

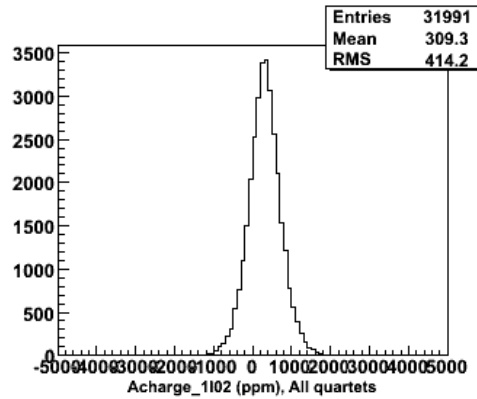
**60 μs**

**10 μs**

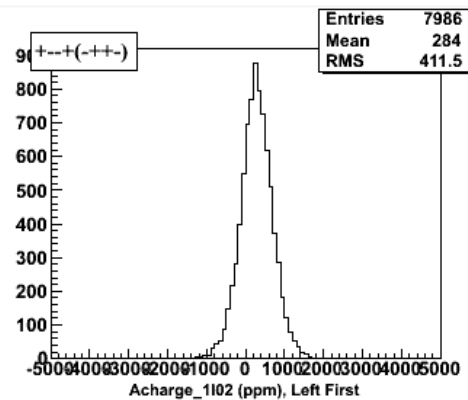
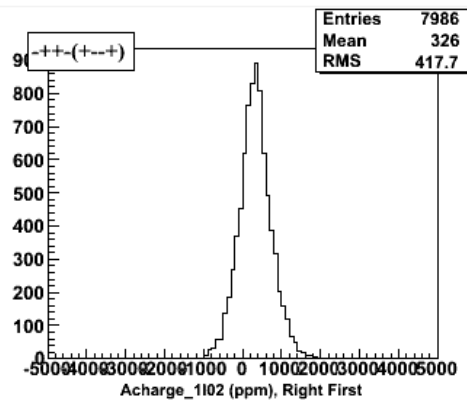
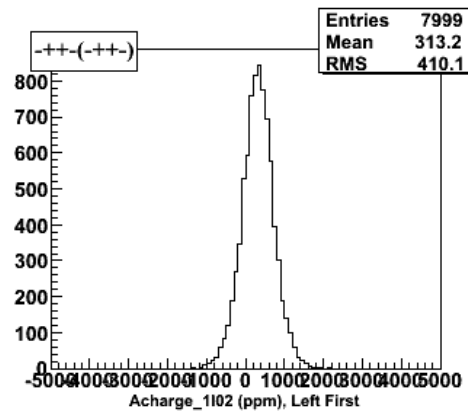
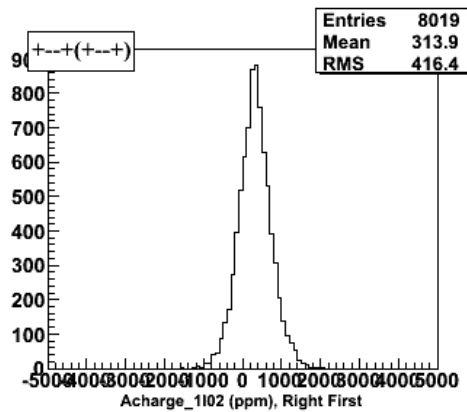
**1 kHz, 500 μs, IN**



# Charge Separation at 1 kHz



Run 710

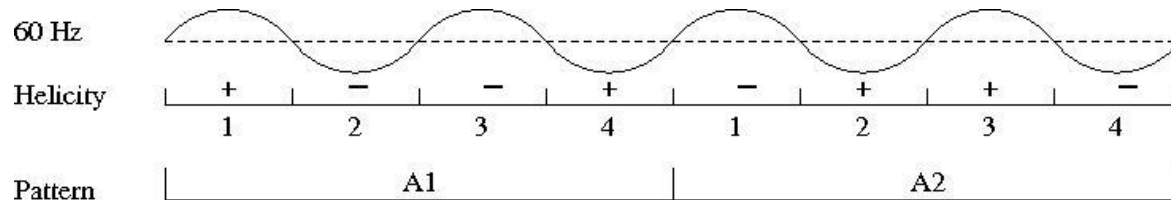


# How to Reduce 60 Hz Line Noise?

1. Choose small  $T_{\text{Stable}}$  (1 ms)  $\rightarrow$  fast helicity reversal (1 kHz)

2. Cancel 60 Hz noise by design:

- Choose  $T_{\text{Stable}} = 33.333$  ms (exactly two 60 Hz cycles). This is 30 Hz (Actually 29.6 Hz) helicity reversal
- Choose  $T_{\text{Stable}} = 16.666$  ms (exactly one 60 Hz cycle). This is 60 Hz helicity reversal
- Choose  $T_{\text{Stable}} + T_{\text{Settle}} = 8.333$  ms (half 60 Hz cycles), select Quartet Pattern, line-phase locked. Then,  $A = +1-2-3+4$  (or  $-1+2+3-4$ ). This is 120 Hz helicity reversal.



- Choose  $T_{\text{Stable}} + T_{\text{Settle}} = 4.167$  ms, select Octet Pattern, line-phase locked. Then,  $A = +1-2-3+4-5+6+7-8$ . This is 240 Hz helicity reversal
- Will patterns compromise cancellation of other low frequency noises?



# Summary

- Fast Helicity Reversal is needed:
  - ✓ Reduces noise from target density fluctuations by huge factor
  - ✓ Reduces noise on beam current by factor of 3
  - ✓ No significant reduction in beam position noise
- Beam Properties at 1 kHz is very similar to 30 Hz and PQB is good
- T\_Settle of 50  $\mu$ s is very reasonable
- Future Parity Experiment:

Experiment	Frequency	Clock	Pattern
HAPPEX III & PVDIS	29.6 Hz	Free	Quartet
PREx	240 Hz	Line-Locked	Octet
QWeak	1 kHz	Free	Quartet

- New Helicity Board to be installed on July 6, 2009

**Backup Slides**

	Chan 1	Chan 2	Chan 3	Chan 4	Chan 5	Chan 6	Chan 7	Chan 8
<b>ADC1</b>	QPD pm	QPD pp	QPD mm	QPD mp		Multi Sync	Battery 1	Battery 2
<b>ADC2</b>	1I02				1I04			
<b>ADC3</b>	1I06				0I02			
<b>ADC4</b>	0I02A				0I05			
<b>ADC5</b>	0I07				0L01			
<b>ADC6</b>	0L02				0L03			
<b>ADC7</b>	0L04				0L05			
<b>ADC8</b>	0L06				0L07			
<b>ADC9</b>	0L08				0L09			
<b>ADC10</b>	0L10				0R03			
<b>ADC11</b>	0R04				0R05			
<b>ADC12</b>	0R06				BCM 0L02	Battery 3	Battery 4	Phase Monitor

Notes:

1. For each BPM, the wires are: +X+, +X-, +Y+, +Y-.
2. There are only two injector BPMs we are not reading: 0R01 and 0R02.

# y-position Differences

(No Outliers)

